

# The Power of Two-Choices in Regulating Interval Partitions

Ohad N. Feldheim (Stanford)  
Joint work with Ori Gurel-Gurevich (HUJI)

September 2016

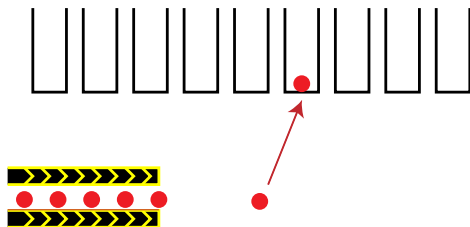
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



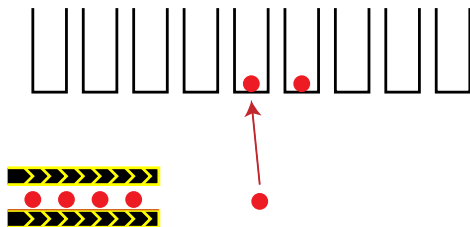
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



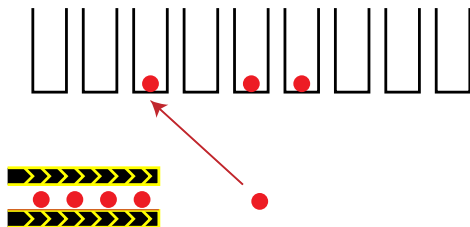
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



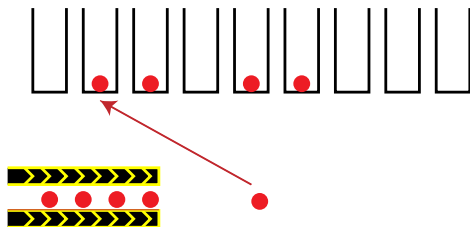
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



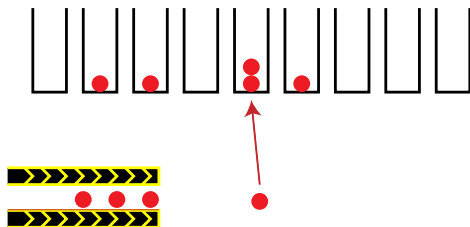
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



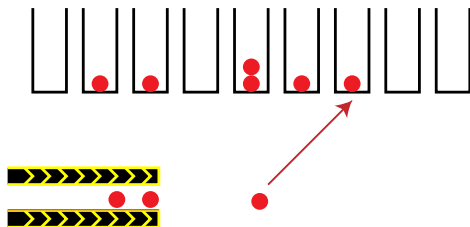
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



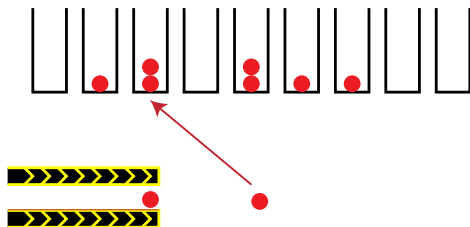
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



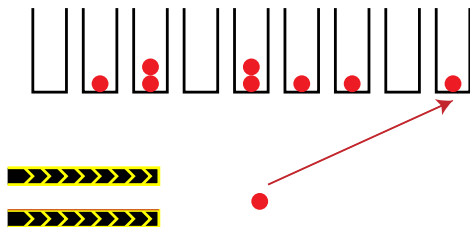
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



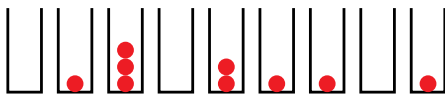
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



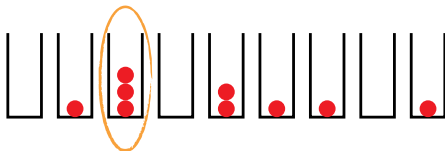
# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



# Balls and bins model

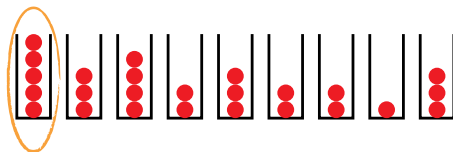
Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



- After  $M$  balls, highest occupancy is a.a.s.  $(1 + o(1)) \frac{\log M}{\log \log M}$

# Balls and bins model

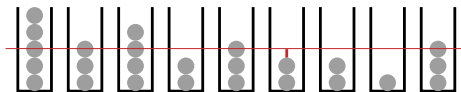
Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



- After  $M$  balls, highest occupancy is a.a.s.  $(1 + o(1)) \frac{\log M}{\log \log M}$
- After  $N \gg M$  balls, highest occupancy is a.a.s.  $\frac{N}{M} + \Theta\left(\sqrt{\frac{N \log M}{M}}\right)$

# Balls and bins model

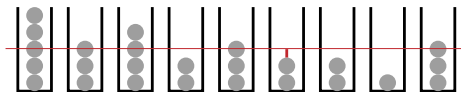
Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



- After  $M$  balls, highest occupancy is a.a.s.  $(1 + o(1)) \frac{\log M}{\log \log M}$
- After  $N \gg M$  balls, highest occupancy is a.a.s.  $\frac{N}{M} + \Theta\left(\sqrt{\frac{N \log M}{M}}\right)$   
typical deviation from expectation is  $\Theta\left(\sqrt{\frac{N}{M}}\right)$

# Balls and bins model

Consider an online process in which  $N$  balls are randomly assigned, one by one to  $M$  bins.



- After  $M$  balls, highest occupancy is a.a.s.  $(1 + o(1)) \frac{\log M}{\log \log M}$
- After  $N \gg M$  balls, highest occupancy is a.a.s.  $\frac{N}{M} + \Theta\left(\sqrt{\frac{N \log M}{M}}\right)$   
typical deviation from expectation is  $\Theta\left(\sqrt{\frac{N}{M}}\right)$
- *Load balancing* is an effort to reduce these quantities.  
(possible with control over the distribution of the balls.)

# Power of two choices

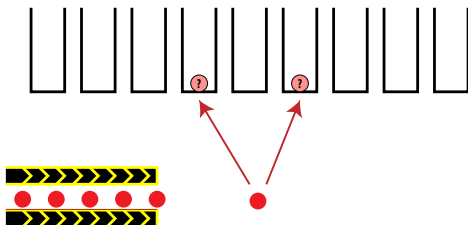
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

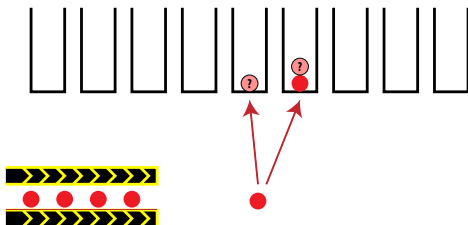
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

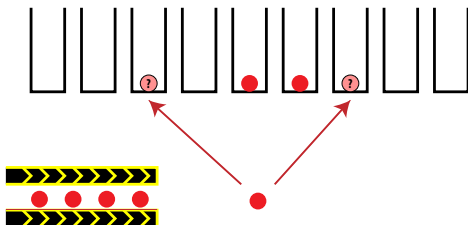
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

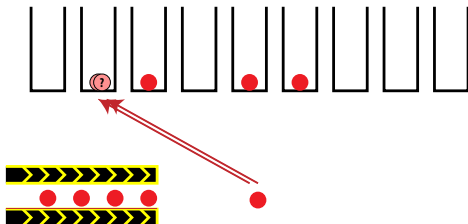
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

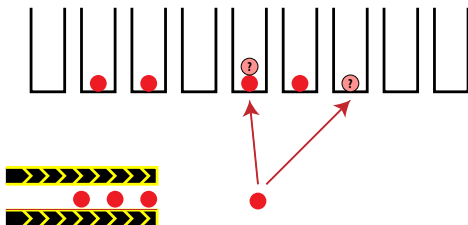
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



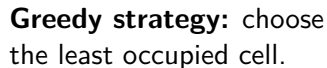
**Greedy strategy:** choose the least occupied cell.

# Power of two choices

**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.

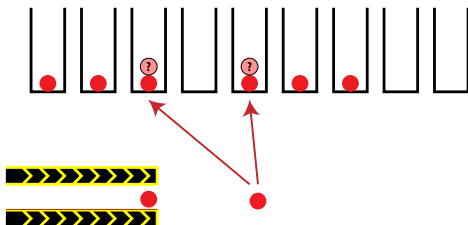


**Greedy strategy:** choose the least occupied cell.



# Power of two choices

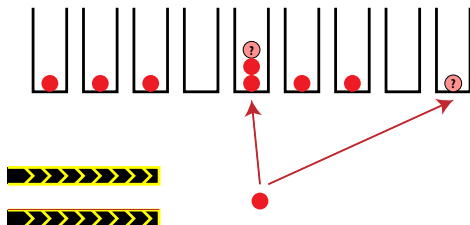
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

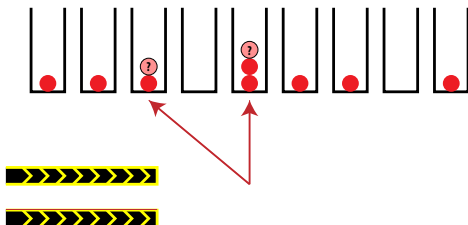
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

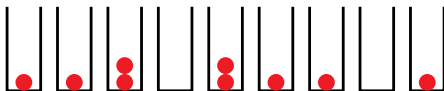
**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

# Power of two choices

**Azar, Broder, Karlin, and Upfal (1994):** Very little choice is sufficient for rather balanced allocation - choice between two random cells per ball.



**Greedy strategy:** choose the least occupied cell.

Balls	no-choice max. dev.	2-choices max. dev.	no-choice typ. dev.	2-choices typ. dev.
$M$	$\frac{\log M}{\log \log M}$	$\frac{\log \log M}{2}$	$O(1)$	$O(1)$
$N \gg M$	$\Theta\left(\sqrt{\frac{N \log M}{M}}\right)$	$\Theta(\log M)$	$\Theta\left(\sqrt{\frac{N}{M}}\right)$	$O(1)$

# Power of two choices - remarks

This observation had many applications

- Server load-balancing
- Distributed shared memory
- Efficient on-line hashing
- Low-congestion circuit routing

# Power of two choices - remarks

This observation had many applications

- Server load-balancing
- Distributed shared memory
- Efficient on-line hashing
- Low-congestion circuit routing

It is interesting to note that

# Power of two choices - remarks

This observation had many applications

- Server load-balancing
- Distributed shared memory
- Efficient on-line hashing
- Low-congestion circuit routing

It is interesting to note that

- More choice does not significantly reduce the maximum load.

# Power of two choices - remarks

This observation had many applications

- Server load-balancing
- Distributed shared memory
- Efficient on-line hashing
- Low-congestion circuit routing

It is interesting to note that

- More choice does not significantly reduce the maximum load.
- If balls keep appearing and dying at rate 1 the phenomenon persists (Luczak & McDiarmid '05)

# Power of two choices - remarks

This observation had many applications

- Server load-balancing
- Distributed shared memory
- Efficient on-line hashing
- Low-congestion circuit routing

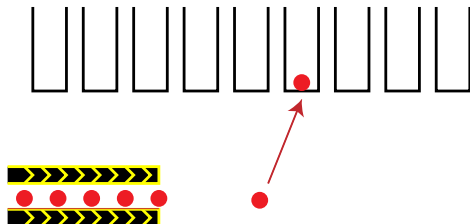
It is interesting to note that

- More choice does not significantly reduce the maximum load.
- If balls keep appearing and dying at rate 1 the phenomenon persists (Luczak & McDiarmid '05)
- However if one can't keep track of the number of balls per bin (due to having  $M^{1-\epsilon}$  bits of memory), then no asymptotic improvement over no-choice is possible (Alon, Gurel-Gurevich, Lubetzky '09)



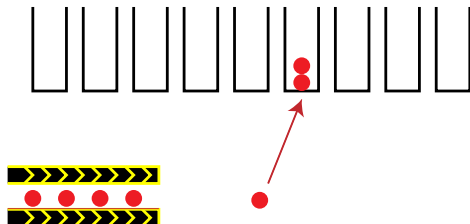
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



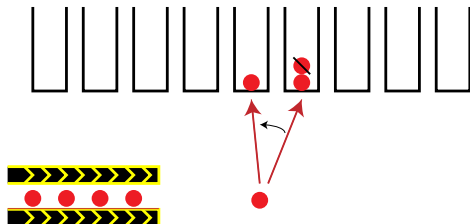
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



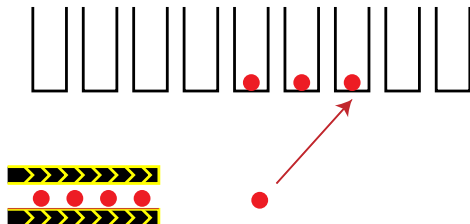
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



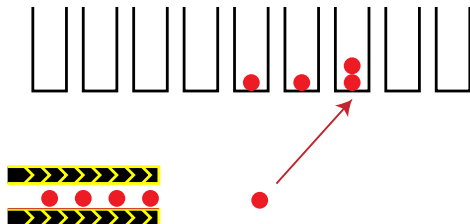
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



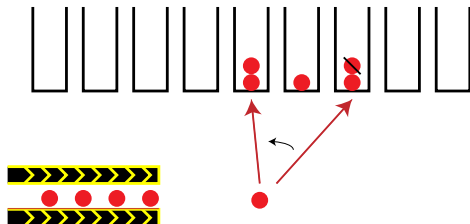
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



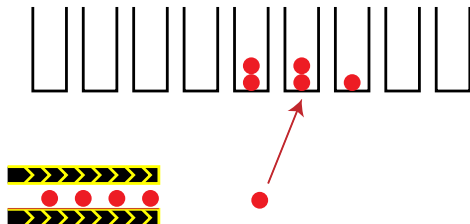
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



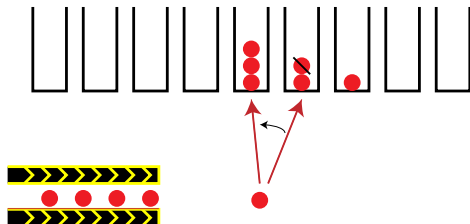
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



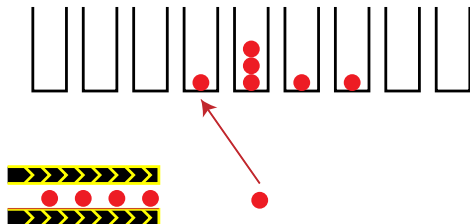
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



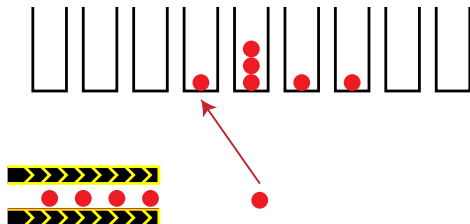
# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



# Two-choices and One-retry

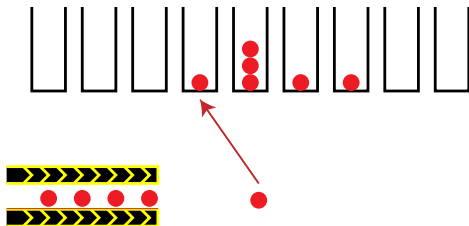
**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



Equivalent to being oblivious to one of the two bins in the two choices setup.

# Two-choices and One-retry

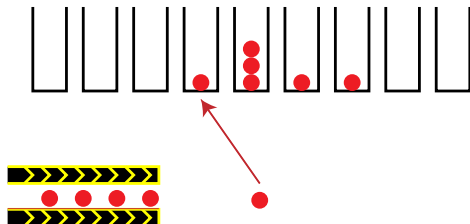
**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



Equivalent to being oblivious to one of the two bins in the two choices setup. Asymptotic discrepancy like two-choices when  $N \gg M$ .

# Two-choices and One-retry

**One-retry:** A related intermediate setup. The chooser is only offered a chance to re-roll the target bin once per ball.



Equivalent to being oblivious to one of the two bins in the two choices setup. Asymptotic discrepancy like two-choices when  $N \gg M$ . When  $N = M$ , the discrepancy is  $\sqrt{\log M / \log \log M}$ .

# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.

We view the points at time  $n$  as each having  $1/n$  mass, call this  $\mu^n$



# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



We view the points at time  $n$  as each having  $1/n$  mass, call this  $\mu^n$

**Convergence to uniform measure:**

$$\lim_{n \rightarrow \infty} \mu^n \stackrel{T.V.}{=} \mathcal{U}[0, 1]$$

# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



We view the points at time  $n$  as each having  $1/n$  mass, call this  $\mu^n$

**Convergence to uniform measure:**

$$\lim_{n \rightarrow \infty} \mu^n \stackrel{T.V.}{=} \mathcal{U}[0, 1]$$

Three natural ways to measure discrepancy/rate of convergence:

# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



We view the points at time  $n$  as each having  $1/n$  mass, call this  $\mu^n$

**Convergence to uniform measure:**

$$\lim_{n \rightarrow \infty} \mu^n \stackrel{T.V.}{=} \mathcal{U}[0, 1]$$

Three natural ways to measure discrepancy/rate of convergence:  
Geometric:

- Interval variation -  $\max_{a,b} |\mu^n((a, b)) - \mu((a, b))|$

# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



We view the points at time  $n$  as each having  $1/n$  mass, call this  $\mu^n$

**Convergence to uniform measure:**

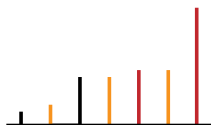
$$\lim_{n \rightarrow \infty} \mu^n \stackrel{T.V.}{=} \mathcal{U}[0, 1]$$

Three natural ways to measure discrepancy/rate of convergence:  
Geometric:

- Interval variation -  $\max_{a,b} |\mu^n((a, b)) - \mu((a, b))|$
- Largest/smallest interval -  $\max_{a,b} |(\mu^n((a, b)) = 0) - 1/n|$

# Interval partition

Consider an online process in which an interval is partitioned into smaller and smaller subintervals by selecting new partition points uniformly at random.



We view the points at time  $n$  as each having  $1/n$  mass, call this  $\mu^n$   
**Convergence to uniform measure:**

$$\lim_{n \rightarrow \infty} \mu^n \stackrel{T.V.}{=} \mathcal{U}[0, 1]$$

Three natural ways to measure discrepancy/rate of convergence:  
Geometric:

- Interval variation -  $\max_{a,b} |\mu^n((a, b)) - \mu((a, b))|$
- Largest/smallest interval -  $\max_{a,b} |(\mu^n((a, b)) = 0) - 1/n|$

Non-geometric:

- Empirical normalized interval distribution.

# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?



# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?

In particular what if we partition the largest interval?

What if we choose the point furthest from neighbour?



# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?

In particular what if we partition the largest interval?

What if we choose the point furthest from neighbour?



# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?

In particular what if we partition the largest interval?

What if we choose the point furthest from neighbour?



# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?

In particular what if we partition the largest interval?

What if we choose the point furthest from neighbour?

Cf. *Kakutani process* - uniform partition of the largest interval.



# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?

In particular what if we partition the largest interval?

What if we choose the point furthest from neighbour?

Cf. *Kakutani process* - uniform partition of the largest interval.



# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?

In particular what if we partition the largest interval?

What if we choose the point furthest from neighbour?

Cf. *Kakutani process* - uniform partition of the largest interval.



# Two-choices and interval partitions

**Benjamini:** Can two choices regulate interval partitions?

In particular what if we partition the largest interval?

What if we choose the point furthest from neighbour?

Cf. *Kakutani process* - uniform partition of the largest interval.



Cf. *Kakutani process* - uniform partition of the largest interval.

Uniform interval partition  $\rightarrow Exp(1)$   
 Kakutani interval partition  $\rightarrow \mathcal{U}(0, 2)$   
 (Pyke 80')

Max-2 interval partition  $\rightarrow$  ???





# Convergence of 2-Max interval partition process

Studying 2-Max is a rather difficult task:

**Maillard & Paquette '14:** 2-Max converges to some limit distribution.

# Convergence of 2-Max interval partition process

Studying 2-Max is a rather difficult task:

**Maillard & Paquette '14:** 2-Max converges to some limit distribution.

**Junge '15:** 2-Max converges to  $U[0, 1]$ .

# Convergence of 2-Max interval partition process

Studying 2-Max is a rather difficult task:

**Maillard & Paquette '14:** 2-Max converges to some limit distribution.

**Junge '15:** 2-Max converges to  $U[0, 1]$ .

Both experimental and heuristic arguments suggest that 2-Max offers no improvement in interval variation when compared with uniform.

# Convergence of 2-Max interval partition process

Studying 2-Max is a rather difficult task:

**Maillard & Paquette '14:** 2-Max converges to some limit distribution.

**Junge '15:** 2-Max converges to  $U[0, 1]$ .

Both experimental and heuristic arguments suggest that 2-Max offers no improvement in interval variation when compared with uniform.

We believe that no **local** algorithm can obtain significant improvement.

# Convergence of 2-Max interval partition process

Studying 2-Max is a rather difficult task:

**Maillard & Paquette '14:** 2-Max converges to some limit distribution.

**Junge '15:** 2-Max converges to  $U[0, 1]$ .

Both experimental and heuristic arguments suggest that 2-Max offers no improvement in interval variation when compared with uniform.

We believe that no **local** algorithm can obtain significant improvement. In a sense, corresponds to Alon, Gurel-Gurevich, Lubetzky.

# Global strategy that regulates interval variation

Our main result is a global one-retry strategy which reduces discrepancy in interval partitions significantly.

# Global strategy that regulates interval variation

Our main result is a global one-retry strategy which reduces discrepancy in interval partitions significantly.

Power of two-choices in regulating interval discrepancy (F. & Gurel-Gurevich 2016+)

In a power of one-retry process on  $\mathcal{U}[0, 1]$ , the chooser can obtain

$$\lim_{n \rightarrow \infty} \mathbb{P} \left( \max_{a,b} |\mu^n((a, b)) - \mu((a, b))| < \frac{C \log^3 N}{N} \right) = 1.$$

# Global strategy that regulates interval variation

Our main result is a global one-retry strategy which reduces discrepancy in interval partitions significantly.

Power of two-choices in regulating interval discrepancy (F. & Gurel-Gurevich 2016+)

In a power of one-retry process on  $\mathcal{U}[0, 1]$ , the chooser can obtain

$$\lim_{n \rightarrow \infty} \mathbb{P} \left( \max_{a,b} |\mu^n((a, b)) - \mu((a, b))| < \frac{C \log^3 N}{N} \right) = 1.$$

- Cf. lower bound of  $\frac{C \log N}{N}$ , no choice estimate  $\sqrt{\frac{C \log N}{N}}$ .

# Global strategy that regulates interval variation

Our main result is a global one-retry strategy which reduces discrepancy in interval partitions significantly.

Power of two-choices in regulating interval discrepancy (F. & Gurel-Gurevich 2016+)

In a power of one-retry process on  $\mathcal{U}[0, 1]$ , the chooser can obtain

$$\lim_{n \rightarrow \infty} \mathbb{P} \left( \max_{a,b} |\mu^n((a, b)) - \mu((a, b))| < \frac{C \log^3 N}{N} \right) = 1.$$

- Cf. lower bound of  $\frac{C \log N}{N}$ , no choice estimate  $\sqrt{\frac{C \log N}{N}}$ .
- There exists a single universal strategy which obtains this for all  $N$ .

# Global strategy that regulates interval variation

The result is obtained through a discrete counterpart which also may be of interest.

# Global strategy that regulates interval variation

The result is obtained through a discrete counterpart which also may be of interest.

## Discrete counterpart

For  $N$  balls on  $\mathcal{U}([M])$ , a probabilistic retry strategy obtains

$$\mathbb{P} \left( \max_{a < b \in [M]} |\mu^n([a, b]) - \mu([a, b])| > \Delta \log^3 M \right) \leq Ce^{-c\Delta}.$$

# Statistical implication

Consider a researcher who is interested in gathering cardiovascular data on a population.

# Statistical implication

Consider a researcher who is interested in gathering cardiovascular data on a population.

- It is well known that this data is correlated with the height of the sampled person.

# Statistical implication

Consider a researcher who is interested in gathering cardiovascular data on a population.

- It is well known that this data is correlated with the height of the sampled person.
- Height test is cheap, cardiovascular test - expensive.

# Statistical implication

Consider a researcher who is interested in gathering cardiovascular data on a population.

- It is well known that this data is correlated with the height of the sampled person.
- Height test is cheap, cardiovascular test - expensive.
- Height distribution in the population is well known.

# Statistical implication

Consider a researcher who is interested in gathering cardiovascular data on a population.

- It is well known that this data is correlated with the height of the sampled person.
- Height test is cheap, cardiovascular test - expensive.
- Height distribution in the population is well known.

One by one volunteers suggest themselves to be tested, and it is desirable to obtain an overall sample which matches the empirical distribution of height.

# Statistical implication

Consider a researcher who is interested in gathering cardiovascular data on a population.

- It is well known that this data is correlated with the height of the sampled person.
- Height test is cheap, cardiovascular test - expensive.
- Height distribution in the population is well known.

One by one volunteers suggest themselves to be tested, and it is desirable to obtain an overall sample which matches the empirical distribution of height.

Our result implies that by rejecting at most one of every two candidates this could be done.

# Stochastic point of view on the power of one-retry





## STOCHASTIC APPROACH TO TWO-CHOICES: REGULATING BALLS AND BINS

# Large family of one-retry distributions

What kind of distributions could be realized using one retry?

# Large family of one-retry distributions

What kind of distributions could be realized using one retry?

## Observation 1

Every distribution with “density”  $\frac{1}{2M} \leq g(x) \leq \frac{3}{2M}$  on  $[M]$  could be realized by a (probabilistic) one-retry strategy.

# Large family of one-retry distributions

What kind of distributions could be realized using one retry?

## Observation 1

Every distribution with “density”  $\frac{1}{2M} \leq g(x) \leq \frac{3}{2M}$  on  $[M]$  could be realized by a (probabilistic) one-retry strategy.

In general any distribution with Radon-Nikodim Derivative w.r.t the base distribution between 0.5 and 1.5 could be realized

# Large family of one-retry distributions

What kind of distributions could be realized using one retry?

## Observation 1

Every distribution with “density”  $\frac{1}{2M} \leq g(x) \leq \frac{3}{2M}$  on  $[M]$  could be realized by a (probabilistic) one-retry strategy.

In general any distribution with Radon-Nikodim Derivative w.r.t the base distribution between 0.5 and 1.5 could be realized

**Proof.** Write  $f(x) = \frac{3}{2} - Mg(x)$ , and retry  $x$  with probability  $f(x)$ .

# Large family of one-retry distributions

What kind of distributions could be realized using one retry?

## Observation 1

Every distribution with “density”  $\frac{1}{2M} \leq g(x) \leq \frac{3}{2M}$  on  $[M]$  could be realized by a (probabilistic) one-retry strategy.

In general any distribution with Radon-Nikodim Derivative w.r.t the base distribution between 0.5 and 1.5 could be realized

**Proof.** Write  $f(x) = \frac{3}{2} - Mg(x)$ , and retry  $x$  with probability  $f(x)$ .  
The probability of a random bin to be re-rolled is  $\sum_{i=1}^M \frac{f(x)}{M} = \frac{1}{2}$ .

# Large family of one-retry distributions

What kind of distributions could be realized using one retry?

## Observation 1

Every distribution with “density”  $\frac{1}{2M} \leq g(x) \leq \frac{3}{2M}$  on  $[M]$  could be realized by a (probabilistic) one-retry strategy.

In general any distribution with Radon-Nikodim Derivative w.r.t the base distribution between 0.5 and 1.5 could be realized

**Proof.** Write  $f(x) = \frac{3}{2} - Mg(x)$ , and retry  $x$  with probability  $f(x)$ .

The probability of a random bin to be re-rolled is  $\sum_{i=1}^M \frac{f(x)}{M} = \frac{1}{2}$ .

Hence the probability that  $x$  is chosen is now

$$\frac{1 - f(x)}{M} + \frac{1}{2M} = g(x)$$



# Self regulating point process

What kind of distributions do we wish to realize?

# Self regulating point process

What kind of distributions do we wish to realize?

- First - how to recover original balls and bins result with  $N \gg M$ .

# Self regulating point process

What kind of distributions do we wish to realize?

- First - how to recover original balls and bins result with  $N \gg M$ .

Consider a point process  $X_t$  with changing causal intensity  $\lambda(t)$ , defined by

$$\lambda(t) = 1 + \theta$$

$$X_t \leq t$$

$$\lambda(t) = 1 - \theta$$

$$X_t > t$$

.

# Self regulating point process

What kind of distributions do we wish to realize?

- First - how to recover original balls and bins result with  $N \gg M$ .

Consider a point process  $X_t$  with changing causal intensity  $\lambda(t)$ , defined by

$$\lambda(t) = 1 + \theta$$

$$X_t \leq t$$

$$\lambda(t) = 1 - \theta$$

$$X_t > t$$

## Proposition

For such a process  $\mathbb{P} \left( |X_t - t| > \frac{\Delta}{\theta} \right) < C\theta^{-2}e^{-\Delta/3}$

# Self regulating point process

What kind of distributions do we wish to realize?

- First - how to recover original balls and bins result with  $N \gg M$ .

Consider a point process  $X_t$  with changing causal intensity  $\lambda(t)$ , defined by

$$\lambda(t) = 1 + \theta$$

$$X_t \leq t$$

$$\lambda(t) = 1 - \theta$$

$$X_t > t$$

## Proposition

For such a process  $\mathbb{P}\left(|X_t - t| > \frac{\Delta}{\theta}\right) < C\theta^{-2}e^{-\Delta/3}$

i.e. for  $\theta < 1$ , such a process has typical fluctuation  $O(\frac{-\log \theta}{\theta})$ .

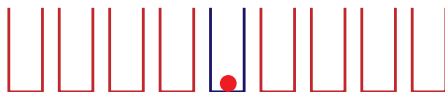
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



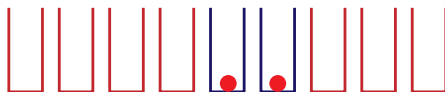
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



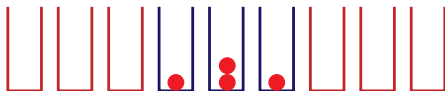
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



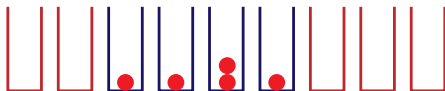
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



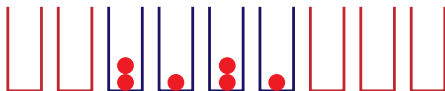
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



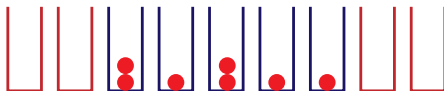
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



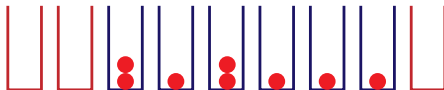
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



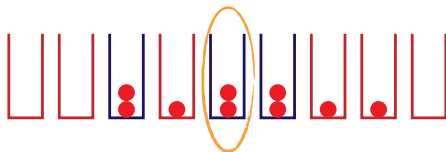
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



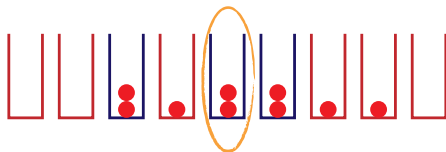
# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



# Recovering the $N \gg M$ balls and bins result

Now let us consider  $M$  such self regulating processes.



Proposition (repeat)

For such a process  $\mathbb{P} \left( |X_t - t| > \frac{\Delta}{\theta} \right) < C\theta^{-2}e^{-\Delta/3}$

Among  $M$  such processes, for fixed  $\theta$ , the extremal fluctuation is  $O(\log M)$ .

# Recovering the $N \gg M$ balls and bins result

**The plan:** realize a self regulating process with  $\theta = 1/5$  at every bin.

# Recovering the $N \gg M$ balls and bins result

**The plan:** realize a self regulating process with  $\theta = 1/5$  at every bin.

Can we do it?

# Recovering the $N \gg M$ balls and bins result

**The plan:** realize a self regulating process with  $\theta = 1/5$  at every bin.

Can we do it?

Yes -  $p_x$ , the probability of the next ball falling into a bin  $x$  is bounded by

$$\frac{1}{2M} \leq \frac{1 - \theta}{M(1 + \theta)} \leq p_x \leq \frac{1 + \theta}{M(1 - \theta)} \leq \frac{3}{2M}.$$

# Recovering the $N \gg M$ balls and bins result

**The plan:** realize a self regulating process with  $\theta = 1/5$  at every bin.

Can we do it?

Yes -  $p_x$ , the probability of the next ball falling into a bin  $x$  is bounded by

$$\frac{1}{2M} \leq \frac{1 - \theta}{M(1 + \theta)} \leq p_x \leq \frac{1 + \theta}{M(1 - \theta)} \leq \frac{3}{2M}.$$

Suppose we use this strategy until time  $N/M$ .  
We expect  $N$  balls, Maximal load of  $N/M + \Theta(\log M)$ .

# Recovering the $N \gg M$ balls and bins result

**The plan:** realize a self regulating process with  $\theta = 1/5$  at every bin.

Can we do it?

Yes -  $p_x$ , the probability of the next ball falling into a bin  $x$  is bounded by

$$\frac{1}{2M} \leq \frac{1 - \theta}{M(1 + \theta)} \leq p_x \leq \frac{1 + \theta}{M(1 - \theta)} \leq \frac{3}{2M}.$$

Suppose we use this strategy until time  $N/M$ .

We expect  $N$  balls, Maximal load of  $N/M + \Theta(\log M)$ .

All that is left is to show that the same holds after  $N$  balls were distributed. - i.e. show concentration of the stopping time.



## STOCHASTIC APPROACH TO TWO-CHOICES: REGULATING INTERVAL PARTITION

# Proving the main Theorem

We will illustrate the proof for discrepancy of  $\log^4 N/N$ , in a continuous setting. The proof in the paper for discrepancy of  $\log^3 N/N$  is similar but requires working with expectations rather than probabilities.

# Balancing poisson point process

Consider two point processes  $X_t^0, X_t^1$  with changing causal intensities  $\lambda^0(t), \lambda^1(t)$  (which may depend on other variables), which satisfy

$$\lambda_t^1, \lambda_t^0 < 2 \quad \forall t$$

$$\lambda_t^0 - \lambda_t^1 \geq \theta \quad X_t^0 \leq X_t^1$$

$$\lambda_t^0 - \lambda_t^1 \leq -\theta \quad X_t^0 > X_t^1$$

# Balancing poisson point process

Consider two point processes  $X_t^0, X_t^1$  with changing causal intensities  $\lambda^0(t), \lambda^1(t)$  (which may depend on other variables), which satisfy

$$\lambda_t^1, \lambda_t^0 < 2 \quad \forall t$$

$$\lambda_t^0 - \lambda_t^1 \geq \theta \quad X_t^0 \leq X_t^1$$

$$\lambda_t^0 - \lambda_t^1 \leq -\theta \quad X_t^0 > X_t^1$$

## Proposition

For such a process  $\mathbb{P} \left( |X_t^1 - X_t^0| > \frac{\Delta}{\theta} \right) < C\theta^{-2}e^{-\Delta/2}$

# Balancing poisson point process

We now define an intensity  $\mu_t$  on  $[0, 1]$  which could be realized by a one-retry strategy.

# Balancing poisson point process

We now define an intensity  $\mu_t$  on  $[0, 1]$  which could be realized by a one-retry strategy.

Each  $(a, b) \subset [0, 1]$  has  $(a, b) = \sum_{i=0}^{\lfloor \log_2 N \rfloor} I_i + R$  where  $I_i$  are diadic and  $|R| < 1/N$ .

# Balancing poisson point process

We now define an intensity  $\mu_t$  on  $[0, 1]$  which could be realized by a one-retry strategy.

Each  $(a, b) \subset [0, 1]$  has  $(a, b) = \sum_{i=0}^{\lfloor \log_2 N \rfloor} I_i + R$  where  $I_i$  are diadic and  $|R| < 1/N$ . For every diadic interval  $I$  write  $I_{\text{left}}, I_{\text{right}}$  for its left and right halves.

# Hierarchy of drifts

We build a hierarchy of  $\log_2 N$  drifts of strength  $C/\log_2 N$ , to control diadic discrepancies.

# Hierarchy of drifts

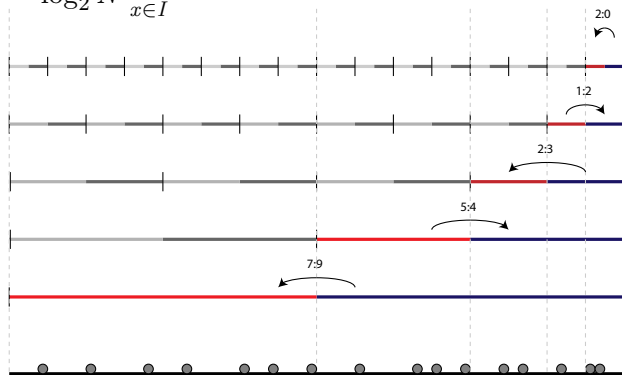
We build a hierarchy of  $\log_2 N$  drifts of strength  $C/\log_2 N$ , to control diadic discrepancies. The intensity of every point  $x$  is

$$1 + \frac{C}{\log_2 N} \sum_{x \in I} \overset{\text{drift hierarchy}}{(-1)^{\mathbf{1}\{x \in I_{\text{left}}\}}} \overset{\text{rate regulating term}}{(-1)^{\mathbf{1}\{\mu_t(I_{\text{left}} \leq I_{\text{right}})\}}} + c(-1)^{\mathbf{1}\{\mu_t([0,1]) > t\}}$$

# Hierarchy of drifts

We build a hierarchy of  $\log_2 N$  drifts of strength  $C/\log_2 N$ , to control diadic discrepancies. The intensity of every point  $x$  is

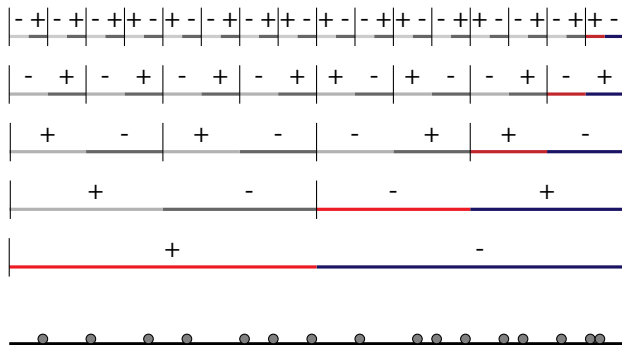
$$1 + \frac{C}{\log_2 N} \sum_{x \in I} \overset{\text{drift hierarchy}}{(-1)^{\mathbf{1}\{x \in I_{\text{left}}\}}} \overset{\text{rate regulating term}}{(-1)^{\mathbf{1}\{\mu_t(I_{\text{left}} \leq I_{\text{right}})\}}} + c(-1)^{\mathbf{1}\{\mu_t([0,1]) > t\}}$$



# Hierarchy of drifts

We build a hierarchy of  $\log_2 N$  drifts of strength  $C/\log_2 N$ , to control diadic discrepancies. The intensity of every point  $x$  is

$$1 + \frac{C}{\log_2 N} \sum_{x \in I} \overset{\text{drift hierarchy}}{(-1)^{\mathbf{1}\{x \in I_{\text{left}}\}}} \overset{\text{rate regulating term}}{(-1)^{\mathbf{1}\{\mu_t(I_{\text{left}} \leq I_{\text{right}})\}}} + c(-1)^{\mathbf{1}\{\mu_t([0,1]) > t\}}$$



# Hierarchy of drifts

We build a hierarchy of  $\log_2 N$  drifts of strength  $C/\log_2 N$ , to control diadic discrepancies. The intensity of every point  $x$  is

$$1 + \frac{C}{\log_2 N} \sum_{x \in I} \overset{\text{drift hierarchy}}{(-1)^{\mathbf{1}\{x \in I_{\text{left}}\}}} \overset{\text{rate regulating term}}{(-1)^{\mathbf{1}\{\mu_t(I_{\text{left}} \leq I_{\text{right}})\}}} + c(-1)^{\mathbf{1}\{\mu_t([0,1]) > t\}}$$

This drift could be made between  $1 - \frac{1}{5}$  and  $1 + \frac{1}{5}$  so that it could be realized by a one-retry strategy as before.

# Hierarchy of drifts - Ct.

Write  $D(I) = \#\{\text{balls in } I_{\text{left}}\} - \#\{\text{balls in } I_{\text{right}}\}$ . By the balancing processes lemma,  $D(I)$  is typically  $(\log_2 n)^2$ .

# Hierarchy of drifts - Ct.

Write  $D(I) = \#\{\text{balls in } I_{\text{left}}\} - \#\{\text{balls in } I_{\text{right}}\}$ . By the balancing processes lemma,  $D(I)$  is typically  $(\log_2 n)^2$ .

We now bound the discrepancy of a diadic interval  $I$  of size  $\frac{1}{2^{j+1}}$  by

$$\sum_{i=0}^{j-1} \frac{1}{2^{j-i}} D(I^i)$$

Where  $I_n^i$  is an interval containing  $I$  of size  $2^{-i}$ .

# Hierarchy of drifts - Ct.

Write  $D(I) = \#\{\text{balls in } I_{\text{left}}\} - \#\{\text{balls in } I_{\text{right}}\}$ . By the balancing processes lemma,  $D(I)$  is typically  $(\log_2 n)^2$ .

We now bound the discrepancy of a diadic interval  $I$  of size  $\frac{1}{2^{j+1}}$  by

$$\sum_{i=0}^{j-1} \frac{1}{2^{j-i}} D(I^i)$$

Where  $I_n^i$  is an interval containing  $I$  of size  $2^{-i}$ . This is also typically of size  $(\log_2 n)^2$ .

# Hierarchy of drifts - Ct.

Write  $D(I) = \#\{\text{balls in } I_{\text{left}}\} - \#\{\text{balls in } I_{\text{right}}\}$ . By the balancing processes lemma,  $D(I)$  is typically  $(\log_2 n)^2$ .

We now bound the discrepancy of a diadic interval  $I$  of size  $\frac{1}{2^{j+1}}$  by

$$\sum_{i=0}^{j-1} \frac{1}{2^{j-i}} D(I^i)$$

Where  $I_n^i$  is an interval containing  $I$  of size  $2^{-i}$ . This is also typically of size  $(\log_2 n)^2$ .

Since any interval with diadic endpoint could be decomposed into at most  $2 \log_2 n$  diadic intervals - the theorem follows.



# Future directions

# Future directions

- Other spaces:  
Benjamini expressed particular interest in whether similar methods could improve discrepancy bounds on a sphere, where the known bounds are far from tight.

# Future directions

- Other spaces:  
Benjamini expressed particular interest in whether similar methods could improve discrepancy bounds on a sphere, where the known bounds are far from tight.
- Other measures of discrepancy.

# Future directions

- Other spaces:  
Benjamini expressed particular interest in whether similar methods could improve discrepancy bounds on a sphere, where the known bounds are far from tight.
- Other measures of discrepancy.
- Reducing the power of the log.

# Future directions

- Other spaces:  
Benjamini expressed particular interest in whether similar methods could improve discrepancy bounds on a sphere, where the known bounds are far from tight.
- Other measures of discrepancy.
- Reducing the power of the log.
- Simpler algorithm?



# THANK YOU.