"Calibeating": Beating Forecasters at Their Own Game

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Joint work with

Dean P. Foster

University of Pennsylvania & Amazon Research NY

Sergiu Hart "Calibration: The Minimax Proof", 1995 [2021]

www.ma.huji.ac.il/hart/publ.html#calib-minmax

Sergiu Hart "Calibration: The Minimax Proof", 1995 [2021]

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www.ma.huji.ac.il/hart/publ.html#calib-minmax
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Dean P. Foster and Sergiu Hart "Smooth Calibration, Leaky Forecasts, Finite Recall, and Nash Dynamics" Games and Economic Behavior 2018

www.ma.huji.ac.il/hart/publ.html#calib-eq

Dean P. Foster and Sergiu Hart "Forecast Hedging and Calibration" Journal of Political Economy 2021

www.ma.huji.ac.il/hart/publ.html#calib-int

Dean P. Foster and Sergiu Hart "Forecast Hedging and Calibration" Journal of Political Economy 2021

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www.ma.huji.ac.il/hart/publ.html#calib-int
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Dean P. Foster and Sergiu Hart "'Calibeating': Beating Forecasters at Their Own Game" Theoretical Economics 2023

www.ma.huji.ac.il/hart/publ.html#calib-beat

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- Forecaster says: "The probability of rain tomorrow is p"
- Forecaster is CALIBRATED if
 - for every forecast p: in the days when the forecast was p, the proportion of rainy days equals p(or: is close to p in the long run)

CALIBRATION can be guaranteed

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(no matter what the weather will be)

Foster and Vohra 1994 [publ 1998]

CALIBRATION can be guaranteed

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- Hart 1995: proof by Minimax Theorem

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CALIBRATION can be guaranteed

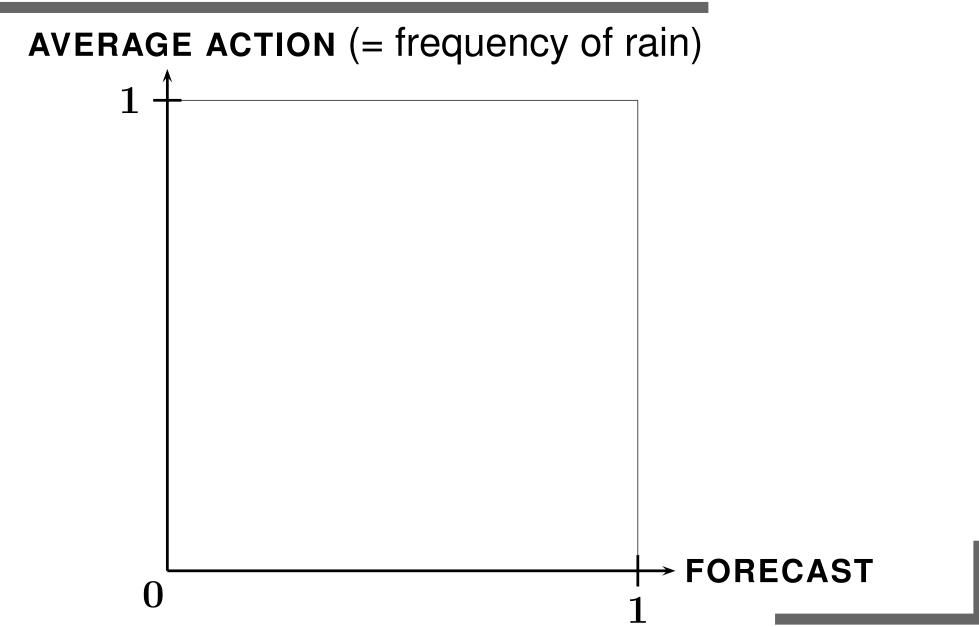
- Foster and Vohra 1994 [publ 1998]
- Hart 1995: proof by Minimax Theorem
- **_**
- Hart and Mas-Colell 1996 [publ 2000]: procedure by Blackwell's Approachability

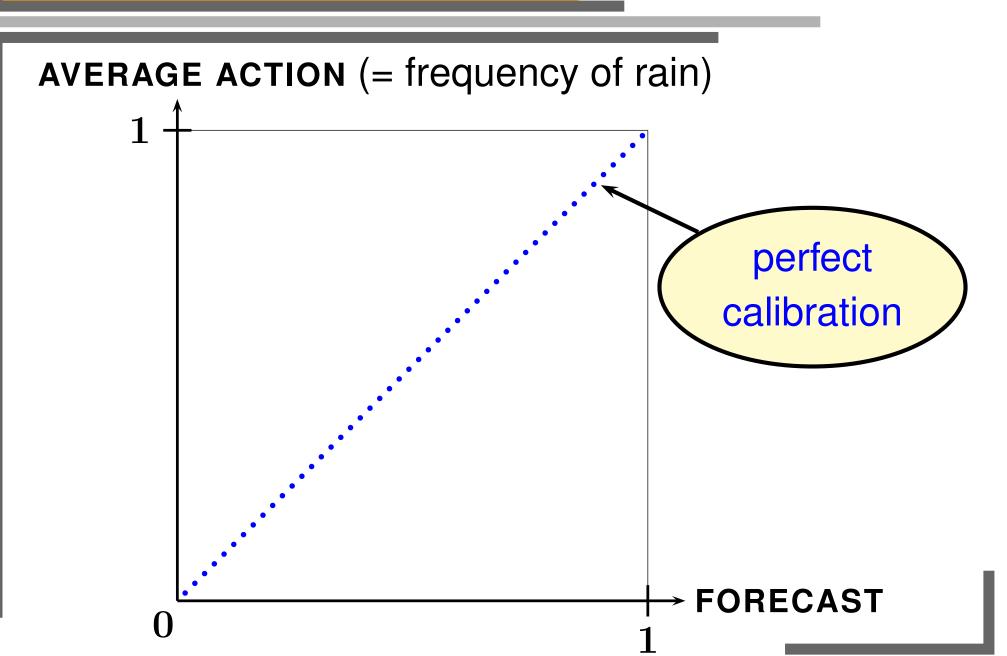
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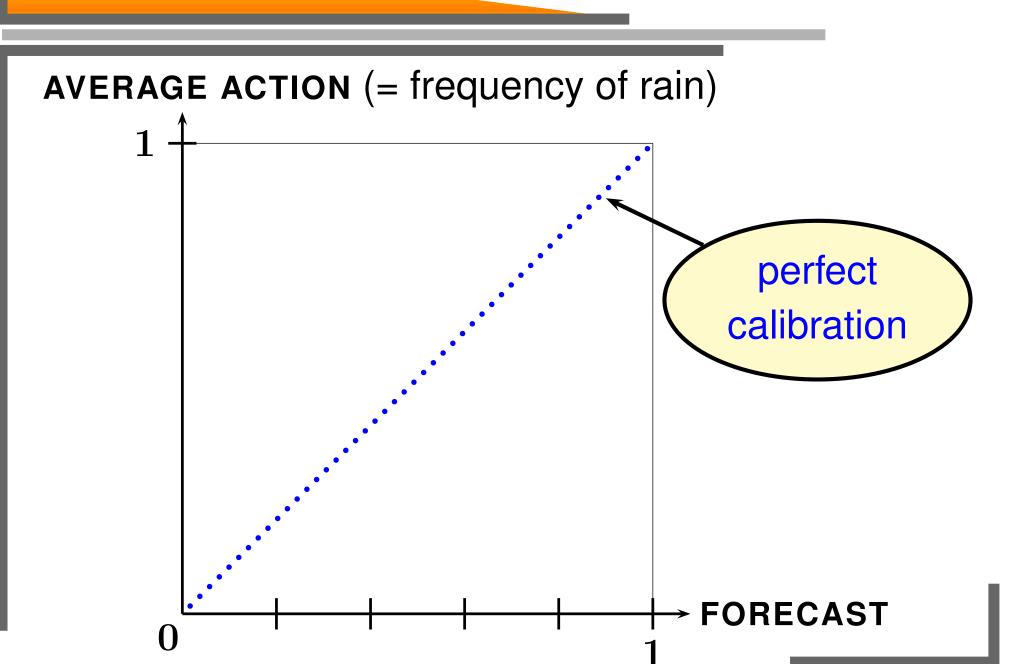
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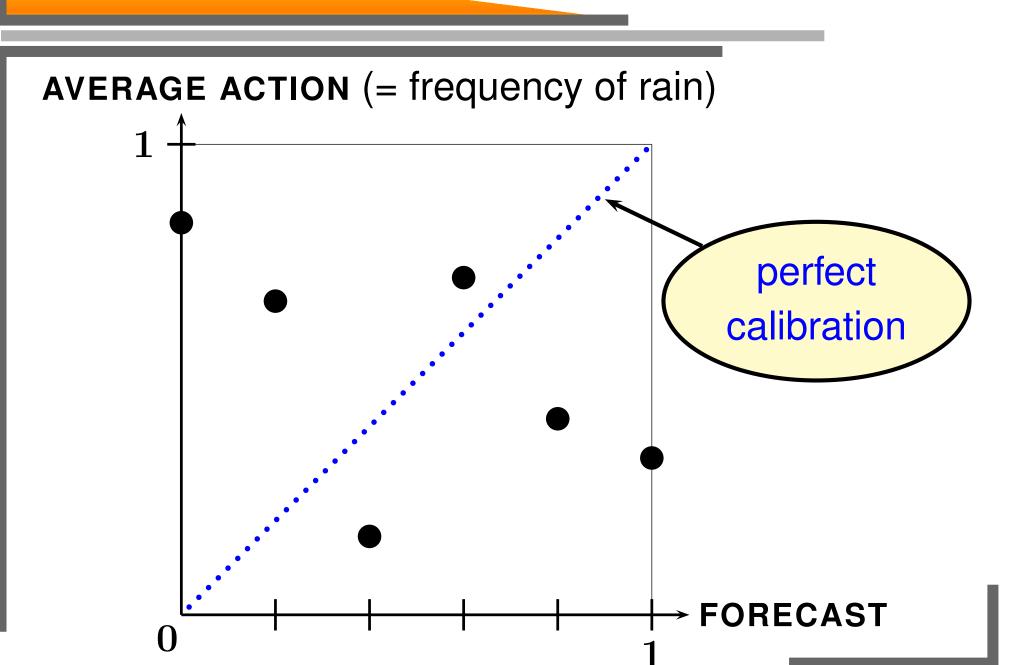
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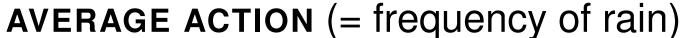
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- Foster 1999: simple procedure
- Foster and Hart 2016 [publ 2021]: simplest procedure, by "Forecast Hedging"

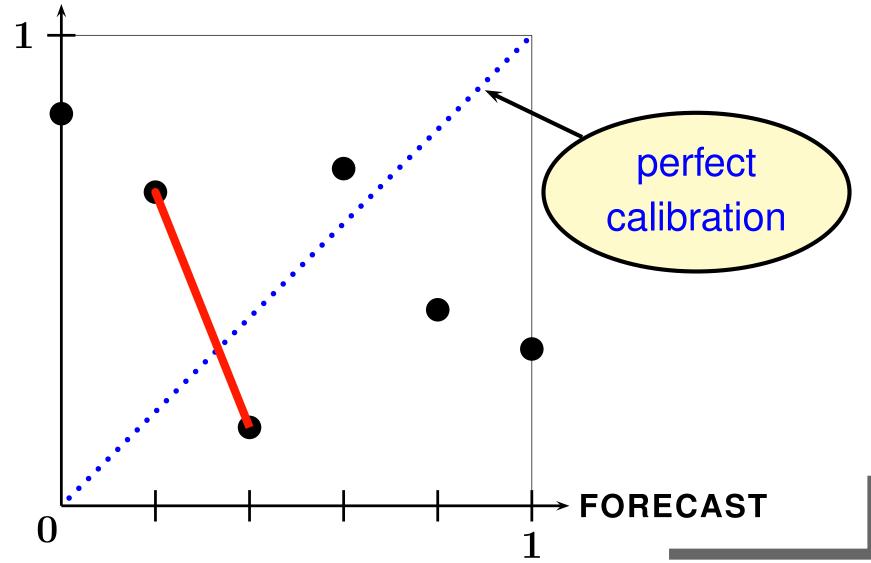


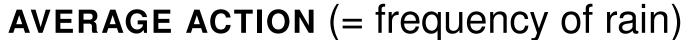


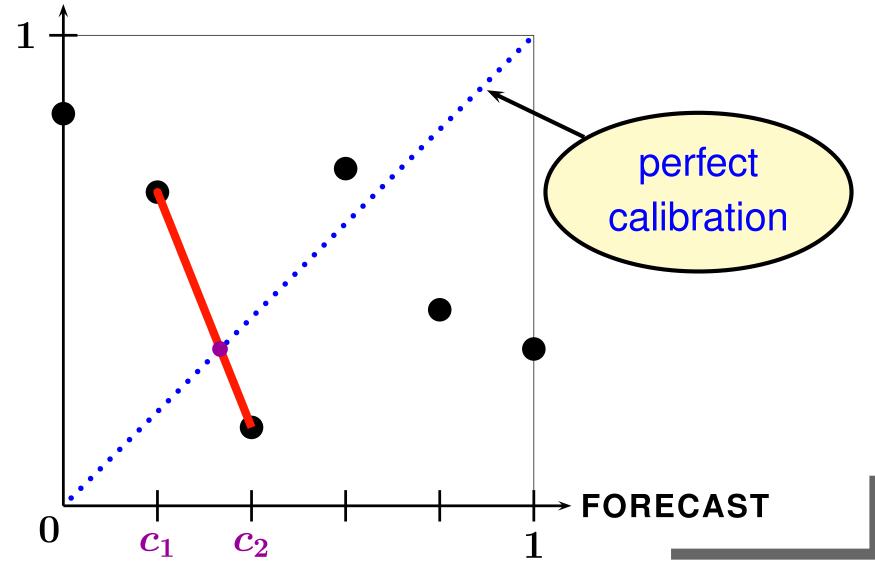






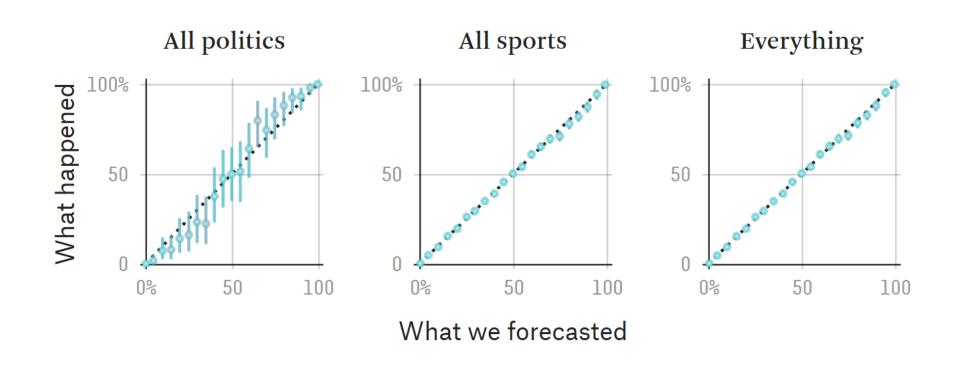






Calibration in Practice

Calibration in Practice



Calibration plots of FiveThirtyEight.com (as of June 2019)

Calibration in Practice



Prediction buckets

Calibration plot of ElectionBettingOdds.com (2016 – 2018)

time | 1 | 2 | 3 | 4 | 5 | 6 | ...

time	$oxed{1}$	2	3	4	5	6	
rain	1	0	1	0	1	0	

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0

F2: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0 IN-BIN VARIANCE = 0

F2: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0 IN-BIN VARIANCE = 0

F2: CALIBRATION = 0 IN-BIN VARIANCE = $\frac{1}{4}$

• $a_t = action at time t$

- $m{a}_t = ext{action at time } t$
- c_t = forecast at time t

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- $ar{a}(x) \equiv ar{a}_T(x) = ext{average of the actions in all}$ periods where the forecast was x

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$$ar{a}(x) = rac{\sum_{t=1}^T \mathbf{1}_x(oldsymbol{c}_t)\,a_t}{\sum_{t=1}^T \mathbf{1}_x(oldsymbol{c}_t)}$$

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$$\mathcal{K} = rac{1}{T} \sum_{t=1}^T \| oldsymbol{c}_t - ar{a}(oldsymbol{c}_t) \|^2$$

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$$\mathcal{R} = rac{1}{T} \sum_{t=1}^T \|a_t - ar{a}(oldsymbol{c}_t)\|^2$$

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BRIER = REFINEMENT + CALIBRATION

Proof.

$$\mathbb{E}[(X-c)^2] = \mathbb{V}ar(X) + (ar{X}-c)^2$$

where c is a constant and $oldsymbol{X}$ is a random variable with $ar{oldsymbol{X}} = \mathbb{E}[oldsymbol{X}]$

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BRIER = REFINEMENT + CALIBRATION

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F1:
$$\mathcal{K} = 0$$
 $\mathcal{R} = 0$

F2:
$$K = 0$$
 $R = \frac{1}{4}$

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1:
$$\mathcal{K} = 0$$
 $\mathcal{R} = 0$ $\mathcal{B} = 0$

F2:
$$K = 0$$
 $R = \frac{1}{4}$ $B = \frac{1}{4}$

Testing experts:

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✓ Brier score

Testing experts:

- **✓ Brier** score
- X CALIBRATION score

"Expertise"

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LOW REFINEMENT SCORE

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Can one GAIN CALIBRATION without LOSING "EXPERTISE"?

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ullet Can one get $\mathcal K$ to 0 without increasing $\mathcal R$?

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- But: CALIBRATION procedures ignore whatever "EXPERTISE" one has

Question:

Can one GAIN CALIBRATION without LOSING "EXPERTISE"?

- Can one get K to 0 without increasing R?
- Can one decrease $\mathcal{B} = \mathcal{R} + \mathcal{K}$ by \mathcal{K} ?

Can one decrease B by K?

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- ▶ **Yes:** Replace each forecast c with the corresponding bin average $\bar{a}(c)$

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 $\mathcal{R}' = \mathcal{R}$ $\mathcal{B}' = \mathcal{B} - \mathcal{K}$

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• IN RETROSPECT / OFFLINE (when the $\bar{a}(c)$ are known)

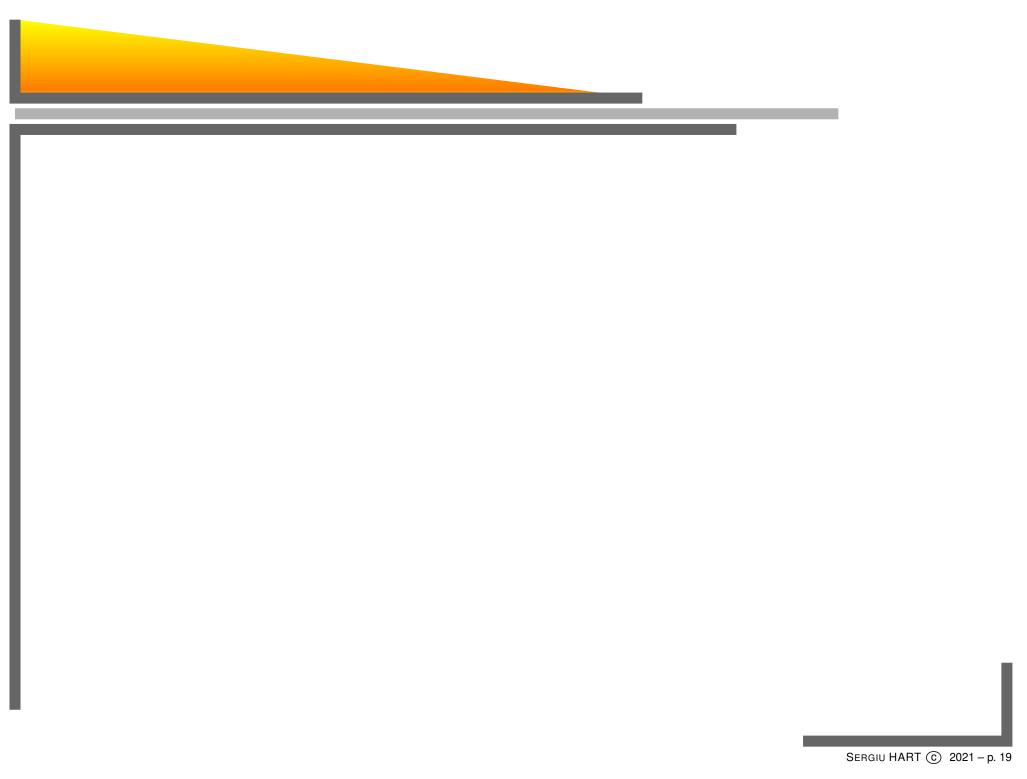
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$$\Rightarrow$$
 $\mathcal{K}^{'}=0$ $\mathcal{R}^{'}=\mathcal{R}$ $\mathcal{B}^{'}=\mathcal{B}-\mathcal{K}$

• IN RETROSPECT / OFFLINE (when the $\bar{a}(c)$ are known)

Question:

Can one do this **ONLINE**?



• Consider a forecasting sequence b_t (in a [finite] set B)

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$$\mathcal{B}_T^{\mathrm{c}} \leq \mathcal{B}_T^{\mathrm{b}} - \mathcal{K}_T^{\mathrm{b}} + \mathrm{o}(1) \quad \mathrm{as} \ T \to \infty$$

for ALL sequences a_t and b_t (uniformly)

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 - ONLINE: use only b_t and history
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 - ONLINE: use only b_t and history
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$$\left| \mathcal{B}^{\mathrm{c}} \leq \mathcal{B}^{\mathrm{b}} - \mathcal{K}^{\mathrm{b}} \right| = \mathcal{R}^{\mathrm{b}}$$

 $oldsymbol{c}$ "BEATS" b by b 's CALIBRATION score

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 - ONLINE: use only b_t and history
 - such that

$$|\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}| = \mathcal{R}^{b}$$

c "BEATS" b by b's CALIBRATION score

GUARANTEED for ALL sequences of actions and forecasts

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
b	80%	40%	80%	40%	80%	40%	

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
b	80%	40%	80%	40%	80%	40%	
		•		•		•	1

b:
$$K^{\rm b} = 0.1$$
 $R^{\rm b} = 0$ $R^{\rm b} = 0.1$

$$\mathcal{R}^{\mathrm{b}}=0$$

$$\mathcal{B}^{\mathrm{b}}=0.1$$

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
\overline{b}	80%	40%	80%	40%	80%	40%	
c	100%	0%	100%	0%	100%	0%	

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$$K^{\rm b} = 0.1$$
 $R^{\rm b} = 0$ $R^{\rm b} = 0.1$

$$\mathcal{R}^{\mathrm{b}} = 0$$

$${\cal B}^{\rm b} = 0.1$$

c:
$$\mathcal{K}^{c} = 0$$
 $\mathcal{R}^{c} = 0$ $\mathcal{B}^{c} = 0$

$$\mathcal{R}^{\mathrm{c}} = 0$$

$$\mathcal{B}^{c}=0$$

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b	80%	40%	80%	40%	80%	40%	
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$$K^{\rm b} = 0.1$$
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$$\mathcal{K}^{c} = 0$$
 $\mathcal{R}^{c} = 0$ $\mathcal{B}^{c} = 0$

$$c$$
 calibeats b : $\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}$

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$$K^{\rm b} = 0.1$$
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 $\mathcal{R}^{c} = 0$ $\mathcal{B}^{c} = 0$

c calibeats b: $\mathcal{B}^{\mathrm{c}} \leq \mathcal{B}^{\mathrm{b}} - \mathcal{K}^{\mathrm{b}} = \mathcal{R}^{\mathrm{b}}$

(that was easy ...)

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Can one CALIBEAT in general, non-stationary, situations?

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Weather is arbitrary and not stationary

(that was easy ...)

- Weather is arbitrary and not stationary
- Forecasts of b are arbitrary

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- **Binning of** b is not perfect ($\mathcal{R}^{b} > 0$)

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- ONLINE

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- Weather is arbitrary and not stationary
- Forecasts of b are arbitrary
- **Binning of** b is not perfect ($\mathcal{R}^{b} > 0$)
- Bin averages do not converge
- ONLINE
- GUARANTEED (even against adversary)

Theorem

There exists a **CALIBEATING** procedure

A Way to Calibeat

A Way to Calibeat

Theorem

The procedure

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

GUARANTEES b-CALIBEATING

A Simple Way to Calibeat

Theorem

The procedure

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

GUARANTEES b-CALIBEATING

Forecast the average action of the current *b*-forecast

$$\mathbb{V} ext{ar} \; = \; rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T
ight\|^2$$

$$\mathbb{V} ext{ar} \ = \ rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T\|^2 \ = \ rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \|x_t - ar{x}_{t-1}\|^2$$

$$\mathbb{V} ext{ar} \ = \ rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T^T\|^2 \ = \ rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
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$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T
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ight\|^2 - \mathrm{o}(1) \end{array}$$

(*)
$$o(1) = O\left(\frac{1}{T}\sum_{t=1}^{T} \frac{1}{t}\right) = O\left(\frac{\log T}{T}\right)$$

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \left\| x_t - ar{x}_{t-1}
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_{t-1}
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Proof: "Online Variance"

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \|x_t - ar{x}_{t-1}\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_{t-1}\|^2 - \mathrm{o}(1) \ &=& \widetilde{\mathbb{V} \mathrm{ar}} & - \mathrm{o}(1) \end{array}$$

Proof: "Online Variance"

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$

Proof: "Online Refinement"

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$
 $\mathcal{R}^\mathrm{b} = \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1)$

Proof: "Online Refinement"

$$egin{array}{lll} \mathbb{V}\mathrm{ar} &=& \widetilde{\mathbb{V}}\mathrm{ar} - \mathrm{o}(1) \ & \mathcal{R}^\mathrm{b} &=& \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1) \ &=& rac{1}{T} \sum_{t=1}^T \|a_t - ar{a}_{t-1}(b_t)\|^2 - \mathrm{o}(1) \end{array}$$

Proof: "Online Refinement"

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$
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 $= \underbrace{\frac{1}{T} \sum_{t=1}^{T} \|a_t - \bar{a}_{t-1}(b_t)\|^2 - \mathrm{o}(1)}_{= \underline{c}_t = \bar{a}_{t-1}(b_t)}$

Theorem

$$\left[oldsymbol{c}_t = ar{a}_{t-1}^{\mathrm{b}}(b_t)
ight]$$

GUARANTEES b-CALIBEATING:

$$\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}$$

Self-Calibeating

Theorem

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

GUARANTEES b-CALIBEATING:

$$\mathcal{B}^{c} < \mathcal{B}^{b} - \mathcal{K}^{b}$$

Theorem

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{c}}(oldsymbol{c}_t)$$

GUARANTEES C-CALIBEATING:

$$\mathcal{B}^{c} < \mathcal{B}^{c} - \mathcal{K}^{c}$$

Self-Calibeating

Theorem

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

GUARANTEES b-CALIBEATING:

$$\mathcal{B}^{\mathrm{c}} \leq \mathcal{B}^{\mathrm{b}} - \mathcal{K}^{\mathrm{b}}$$

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GUARANTEES C-CALIBEATING:

$$\mathcal{B}^{c} \leq \mathcal{B}^{c} - \mathcal{K}^{c}$$

 $\Leftrightarrow \mathcal{K}^{c} = 0$

Self-Calibeating = Calibrating

Theorem

$$oxed{c_t = ar{a}_{t-1}^{\mathrm{b}}(b_t)}$$

GUARANTEES b-CALIBEATING:

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$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{c}}(oldsymbol{c}_t)$$

GUARANTEES CALIBRATION:

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How do we get c_t "close to" $\bar{a}_{t-1}(c_t)$?

How do we get c_t "close to" $\bar{a}_{t-1}(c_t)$?

- $m{Q} \subset \mathbb{R}^m$ compact convex
- $D \subset C$ finite δ -grid of C (for $\delta > 0$)
- $m{g}: m{D}
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Theorem There exists a probability distribution ${\color{red}P}$ on the δ -grid ${\color{red}D}$ of ${\color{red}C}$ such that

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$$\mathbb{E}_{\boldsymbol{x} \sim \boldsymbol{P}} \left[\left\| \boldsymbol{v} - \boldsymbol{x} \right\|^2 - \left\| \boldsymbol{v} - \boldsymbol{g}(\boldsymbol{x}) \right\|^2 \right] \leq \delta^2 \quad \forall \boldsymbol{v} \in \boldsymbol{C}$$

Stochastic "Fixed Point"

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Obtained by solving a Minimax problem (LP)

Outgoing Minimax (FH)

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- Obtained by solving a MINIMAX problem (LP)
- Moreover: solving a FIXED POINT problem yields a probability distribution η that is **ALMOST DETERMINISTIC**: its support is included in a ball of size δ

Theorem

There is a stochastic procedure that **GUARANTEES CALIBRATION**

Theorem

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Proof. Self-calibeating + Outgoing Minimax

Theorem

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Proof. Self-calibeating + Outgoing Minimax

Note. δ -CALIBRATION

Theorem

There is a stochastic procedure that **GUARANTEES CALIBEATING**

Theorem

There is a stochastic procedure that **GUARANTEES CALIBEATING** and **CALIBRATION**

Theorem

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Proof. Calibeat the **joint** binning of b and c, by the Outgoing Minimax theorem

Theorem

There is a *deterministic* procedure that **GUARANTEES CALIBEATING**

Theorem

There is a *deterministic* procedure that **GUARANTEES CALIBEATING** and **CONTINUOUS CALIBRATION**

Theorem

There is a *deterministic* procedure that **GUARANTEES CALIBEATING** and **CONTINUOUS CALIBRATION**

Proof. Calibeat the **joint** binning of b and c, by the Outgoing Fixed Point theorem

Theorem

There is a *deterministic* procedure that **GUARANTEES**

simultaneous CALIBEATING of several forecasters

Theorem

There is a **stochastic** procedure that **GUARANTEES**

simultaneous CALIBEATING of several forecasters

and **CALIBRATION**

Theorem

There is a **stochastic** procedure that **GUARANTEES**

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Proof. Calibeat the joint binning

In all the results above:

In all the results above:

	CALIBRATION	
Obtained by	Minimax	
Procedure	stochastic	

... and Continuous Calibration

In all the results above:

	CALIBRATION	CONTINUOUS
Obtained by	Minimax	Fixed Point
Procedure	stochastic	deterministic

TAKING PRIDE IN OUR RECORD

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"We have correctly forecasted 8 of the last 5 recessions"



TAKING PRIDE IN OUR RECORD

"We have correctly forecasted 8 of the last 5 recessions"