

# Forecast-Hedging and Calibration

**Sergiu Hart**

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**Joint work with**

***Dean P. Foster***

**University of Pennsylvania &  
Amazon**

# Paper

- Dean P. Foster and Sergiu Hart  
“Forecast Hedging and Calibration”
- *Journal of Political Economy* 2021

[www.ma.huji.ac.il/hart/publ.html#calib-int](http://www.ma.huji.ac.il/hart/publ.html#calib-int)

# Other Papers

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- Sergiu Hart  
“Calibration: The Minimax Proof”, 1995 [2021]  
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[www.ma.huji.ac.il/hart/publ.html#calib-minmax](http://www.ma.huji.ac.il/hart/publ.html#calib-minmax)
- Dean P. Foster and Sergiu Hart  
“Smooth Calibration, Leaky Forecasts, Finite Recall, and Nash Dynamics”  
*Games and Economic Behavior* 2018  
[www.ma.huji.ac.il/hart/publ.html#calib-eq](http://www.ma.huji.ac.il/hart/publ.html#calib-eq)

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- Dean P. Foster and Sergiu Hart  
“ ‘Calibeating’: Beating Forecasters at Their Own Game”, 2021  
[www.ma.huji.ac.il/hart/publ.html#calib-beat](http://www.ma.huji.ac.il/hart/publ.html#calib-beat)



# Calibrated Forecasts

# Calibration

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- Forecaster says:  
"There is a 70% chance of rain tomorrow"

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- Forecaster says:  
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- Forecaster says:  
"There is a  $p$  chance of rain tomorrow"
- Forecaster is **CALIBRATED** if
  - For every  $p$ :  
The proportion of rainy days among those days when the forecast was  $p$  equals  $p$   
(or: is close to  $p$  in the long run)

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- Forecaster uses *mixed* forecasting  
(e.g.: with probability  $1/2$ , forecast = 25%  
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# The MINIMAX Theorem

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**THEOREM** (von Neumann 1928)

**IF**

$X \subset \mathbb{R}^n$ ,  $Y \subset \mathbb{R}^m$  are compact convex sets,  
and  $f : X \times Y \rightarrow \mathbb{R}$  is a continuous function  
that is convex-concave,

i.e.,  $f(\cdot, y) : X \rightarrow \mathbb{R}$  is convex for fixed  $y$ ,  
and  $f(x, \cdot) : Y \rightarrow \mathbb{R}$  is concave for fixed  $x$ ,

**THEN**

$$\min_{x \in X} \max_{y \in Y} f(x, y) = \max_{y \in Y} \min_{x \in X} f(x, y).$$

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- finite game; probabilistic (mixed) strategies

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  - Foster 1999: simple procedure
  - Foster and Hart 2016 [**2021**]: even simpler

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Oakes 1985

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Foster and Kakade (2004, 2006)  
Foster and Hart (2018, **2021**)



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- Change in  $S = (G(q) + a - q)^2 - G(q)^2$ 
  - First-order approximation =  $2\Delta$ , where

$$\Delta := G(q) \cdot (a - q)$$

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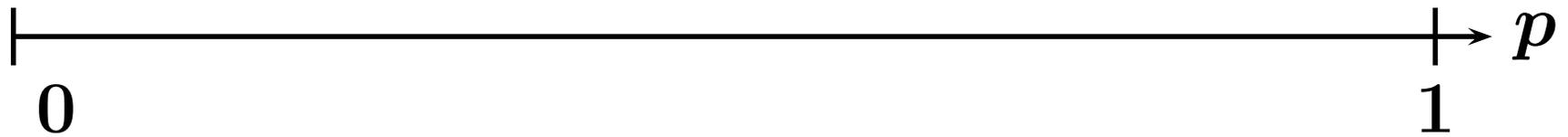
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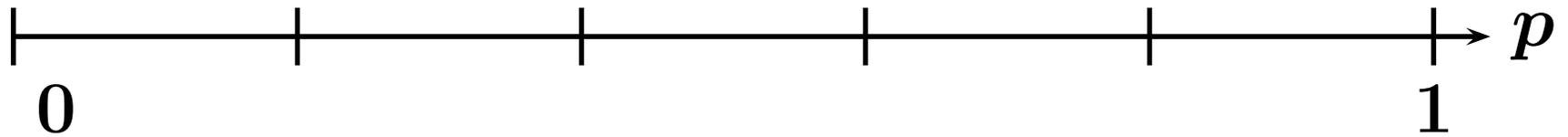
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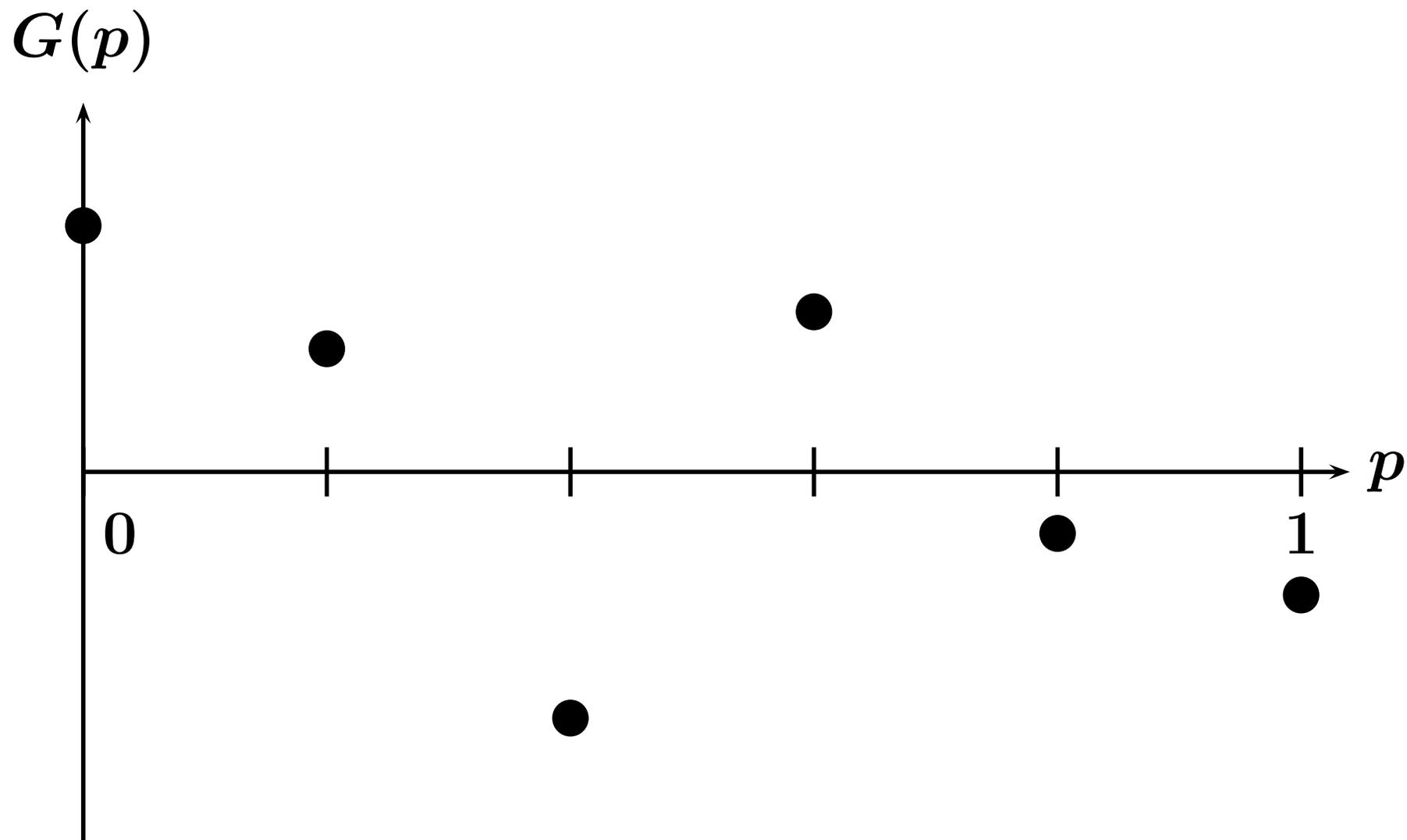
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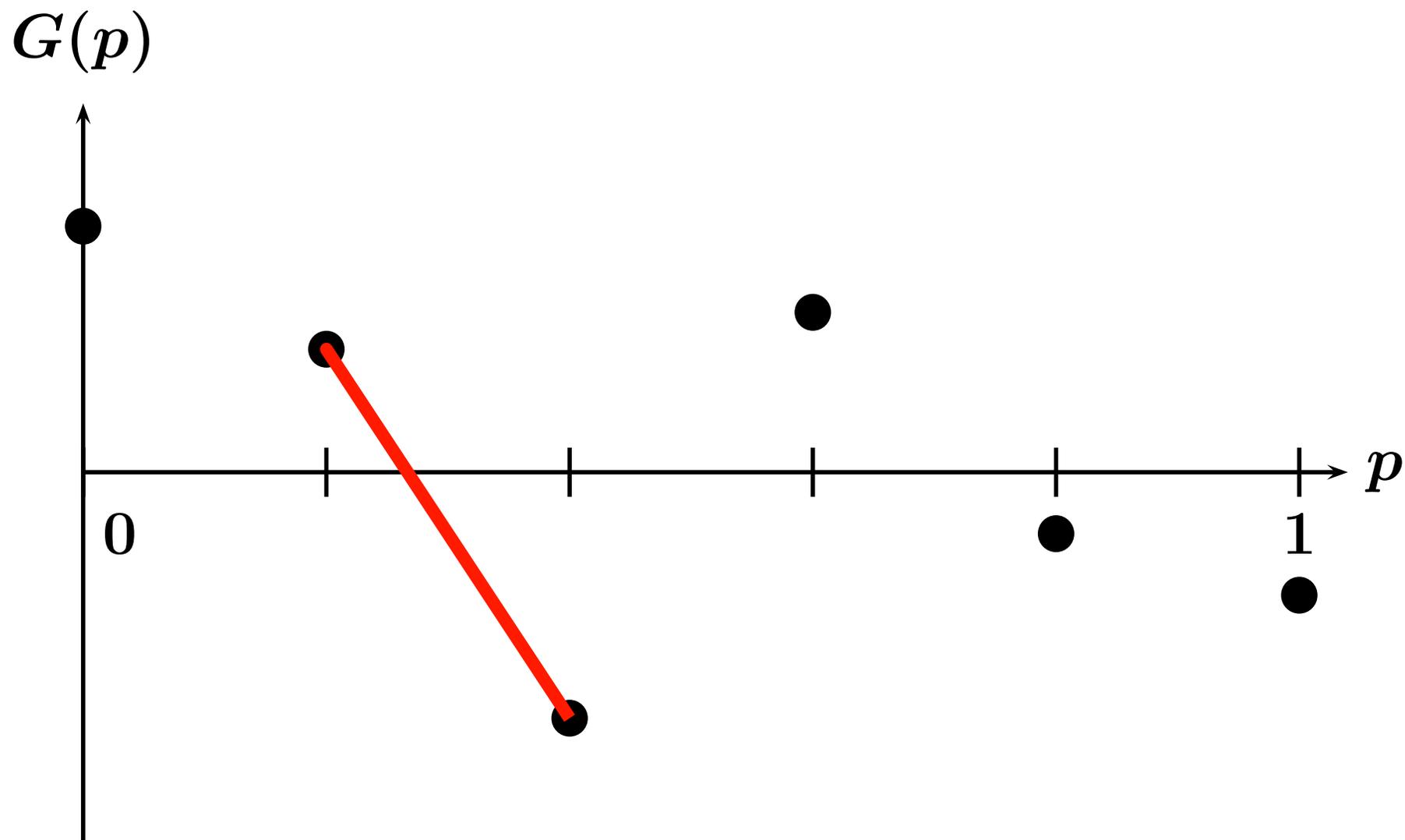
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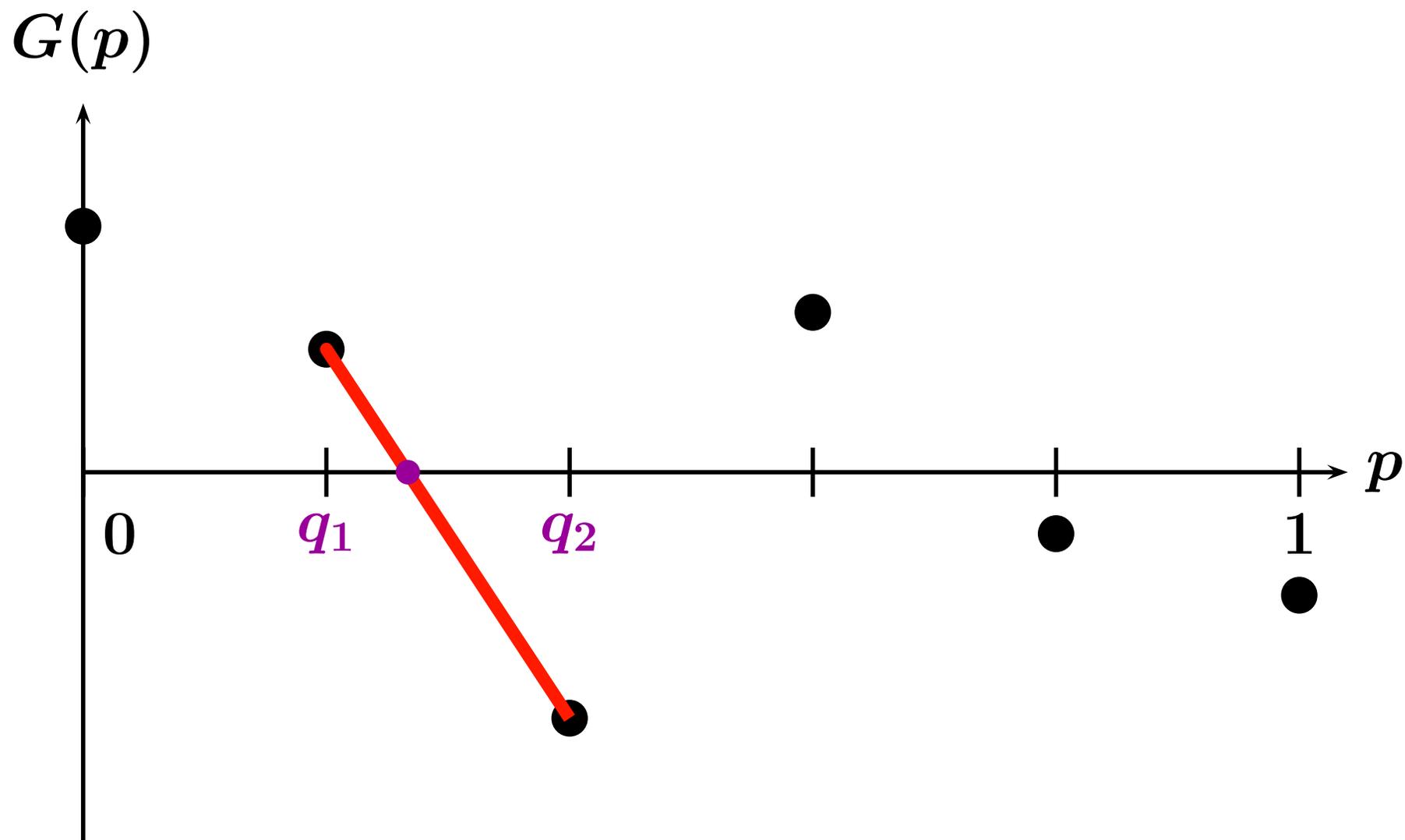
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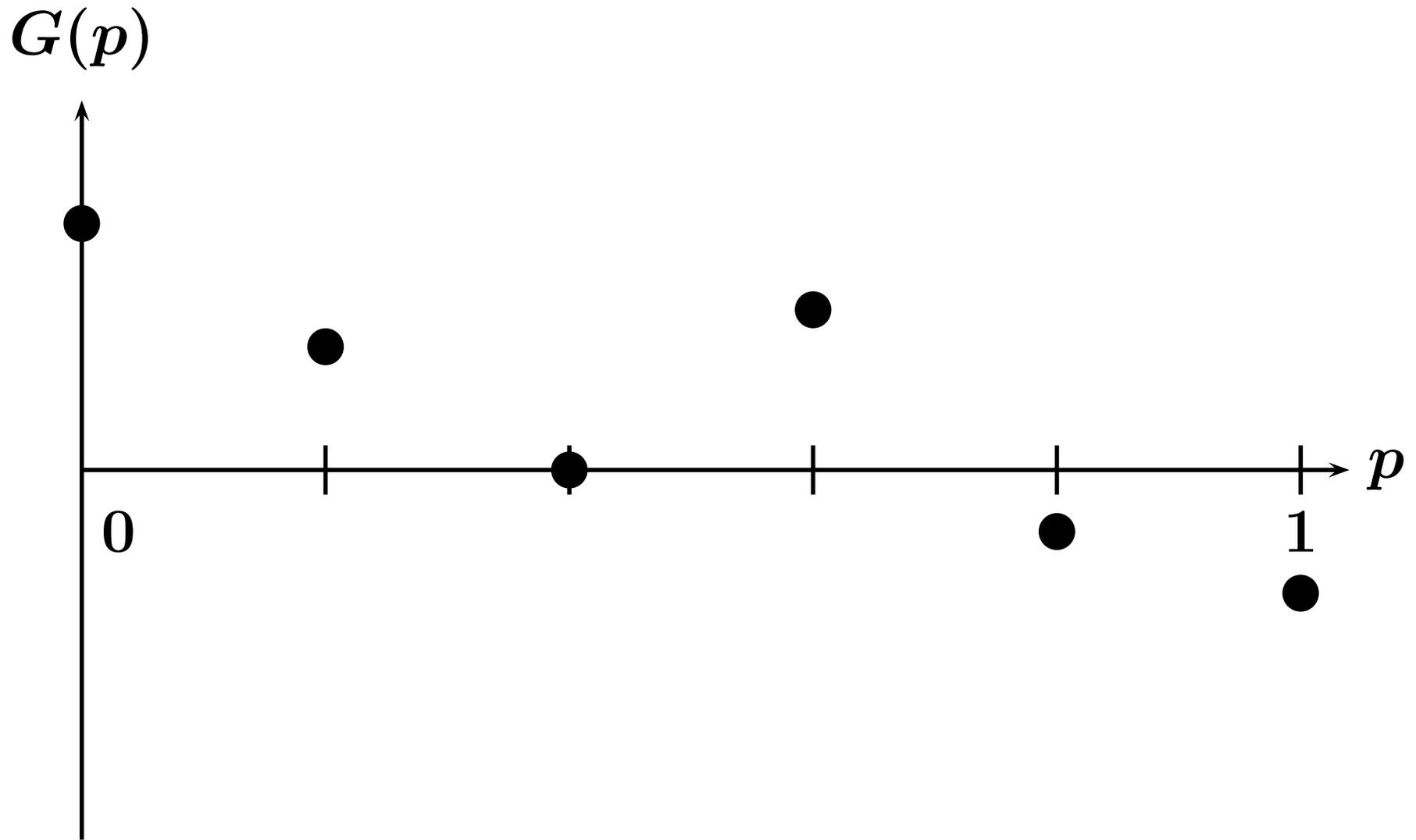


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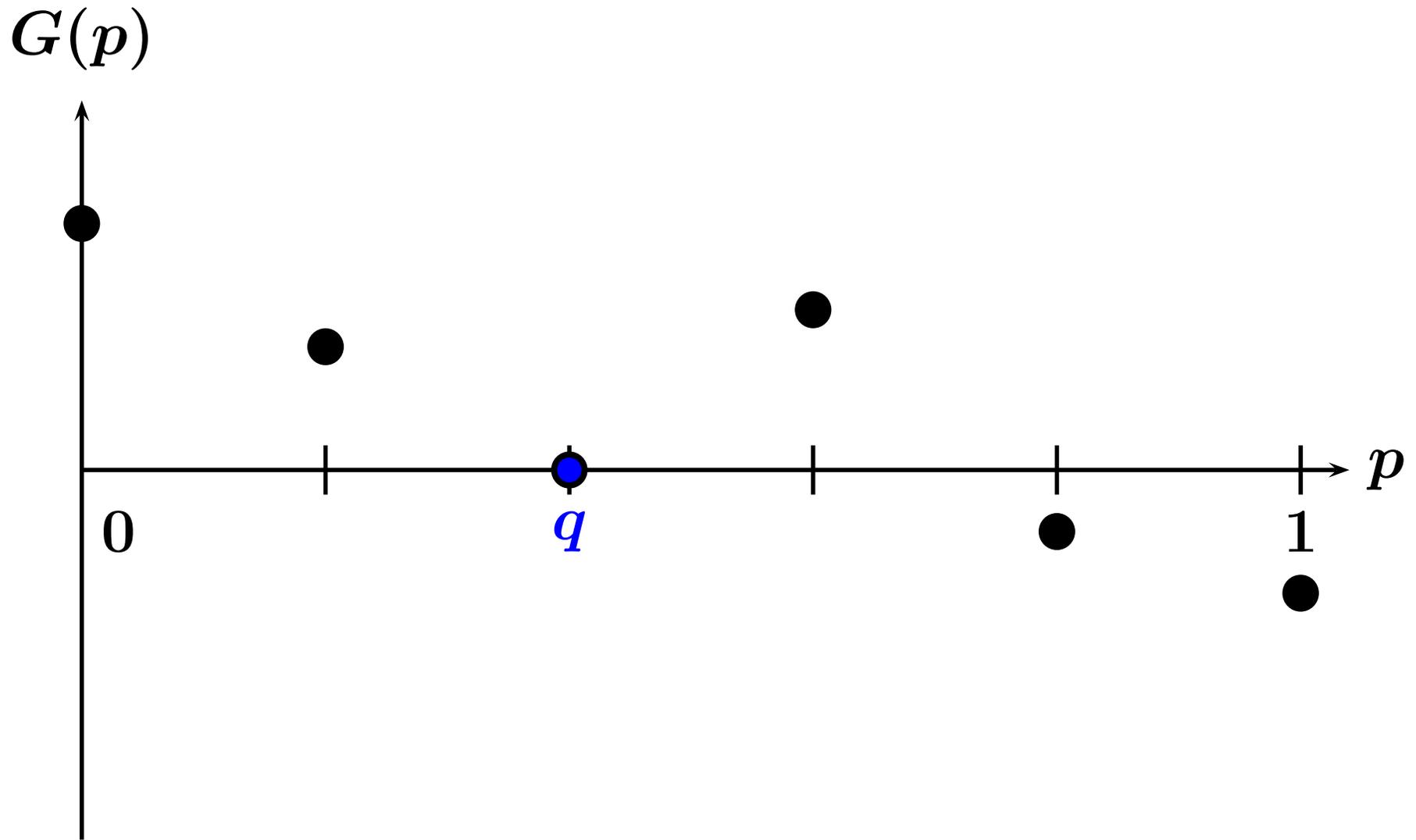


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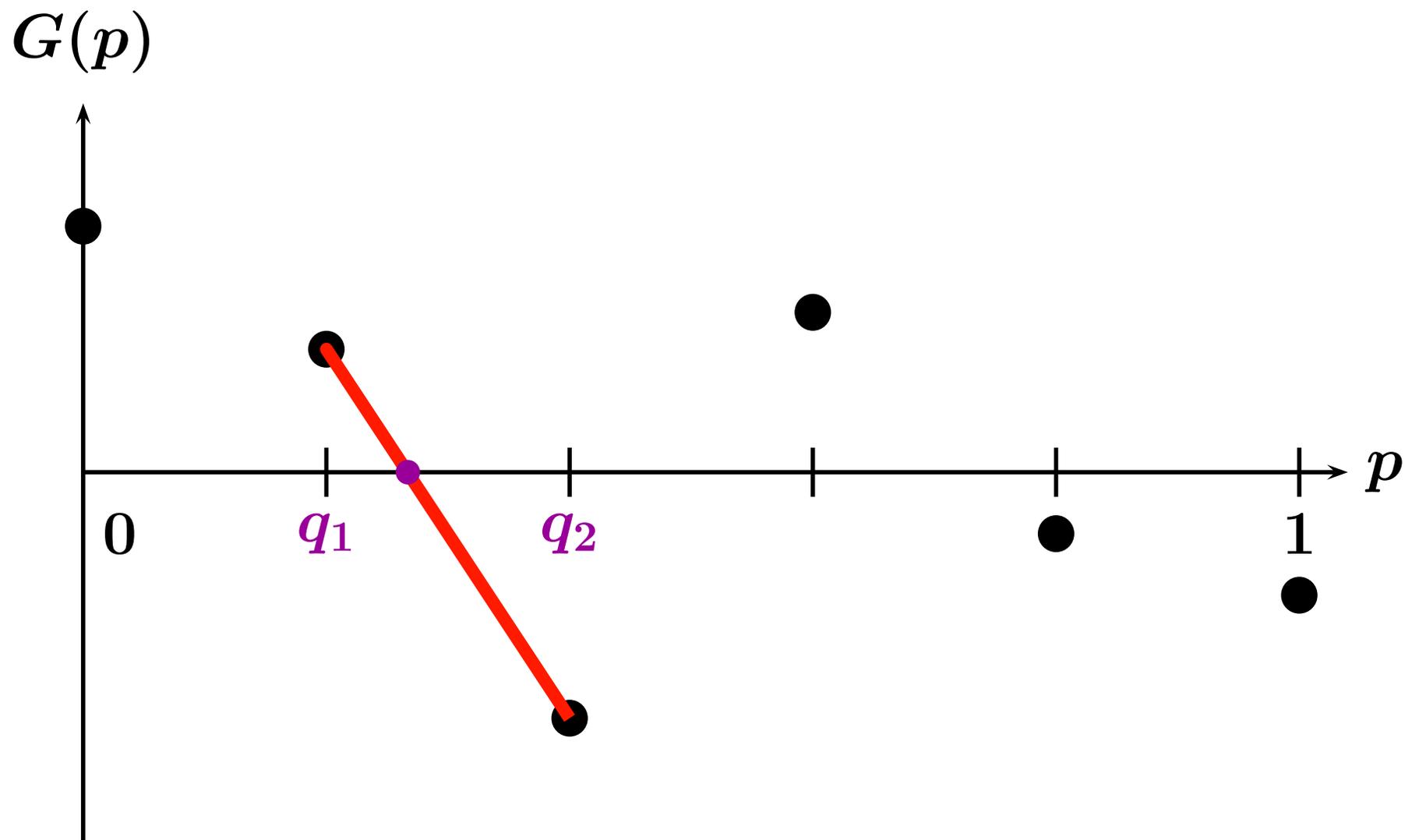
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- **DETERMINISTIC FORECAST-HEDGING**

$$G(q) \cdot (a - q) \leq 0 \text{ for all } a$$

is obtained by continuous **FIXEDPOINT**

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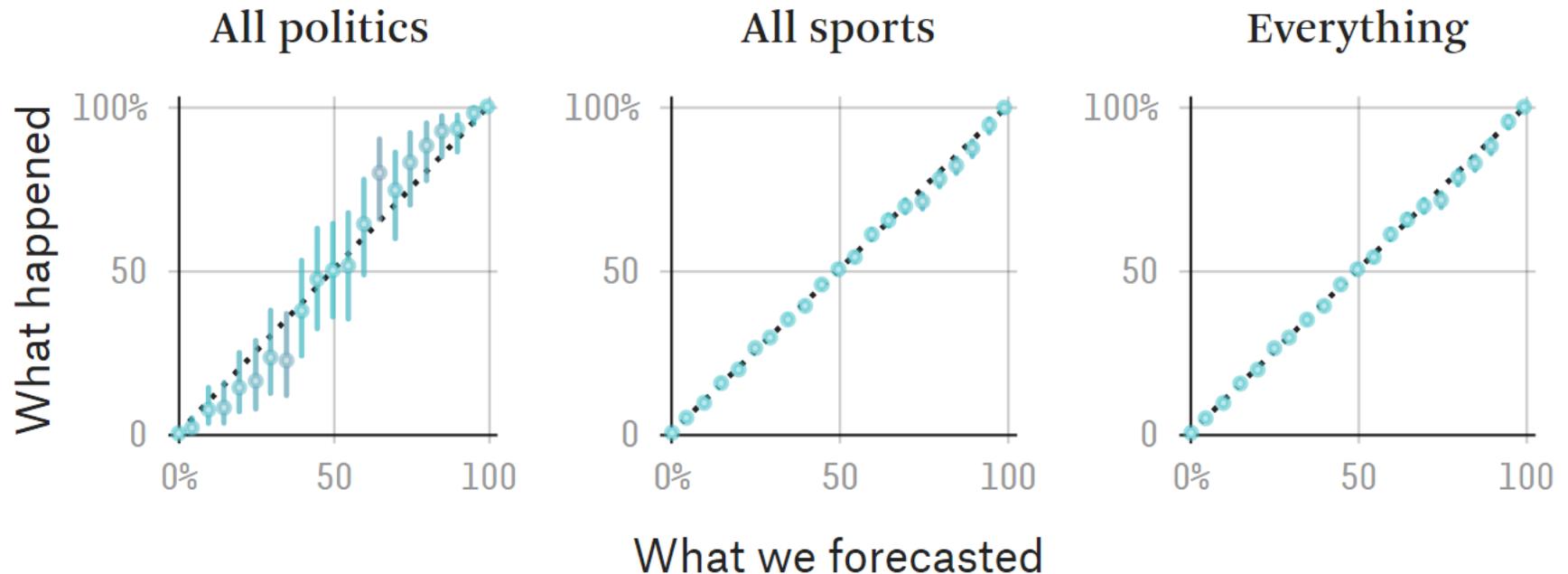
- forecasting ?

# Forecast-Hedging

- fore-casting ?
- **BACK-CASTING !**  
("Politicians' Lemma")

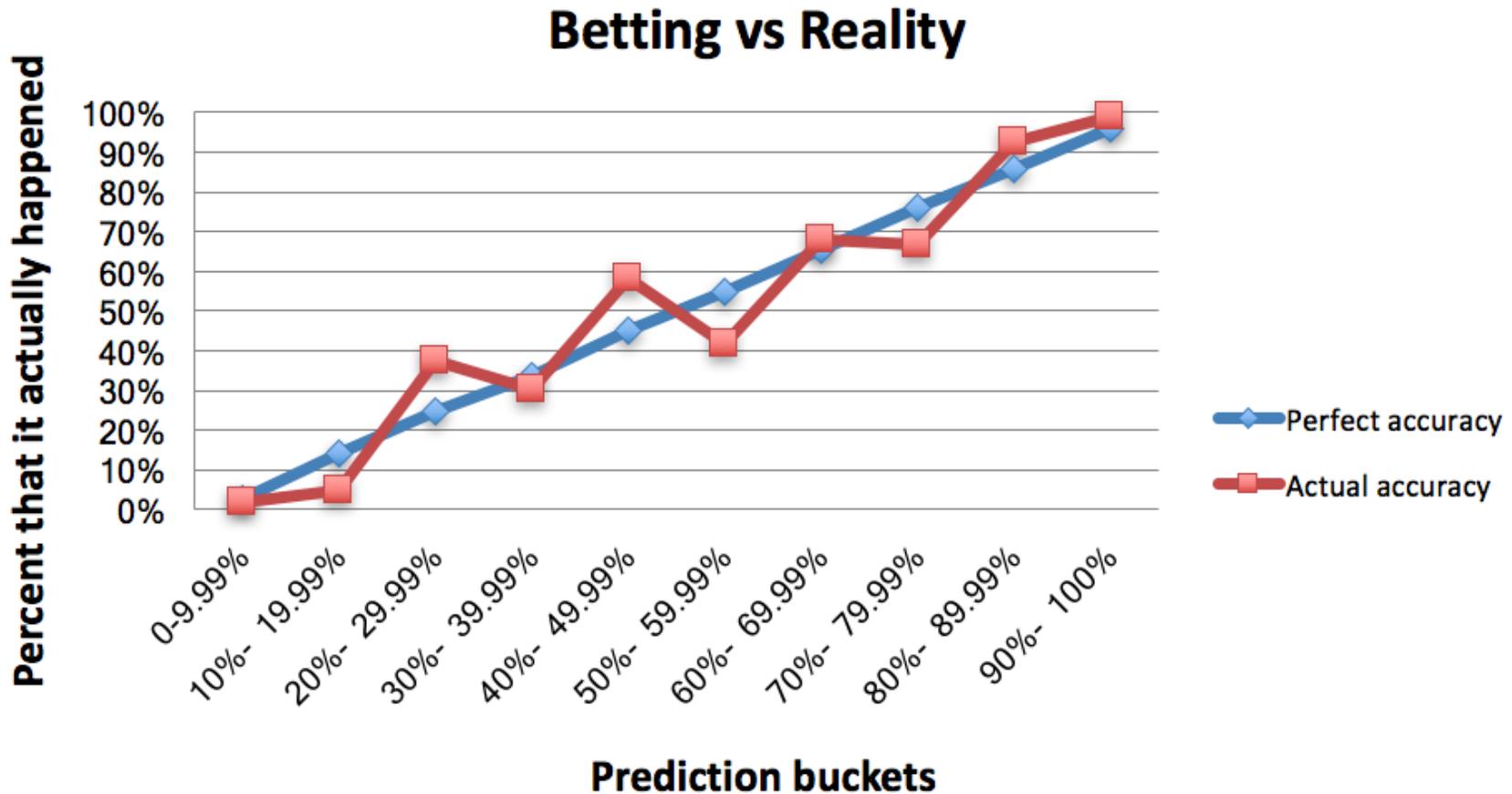
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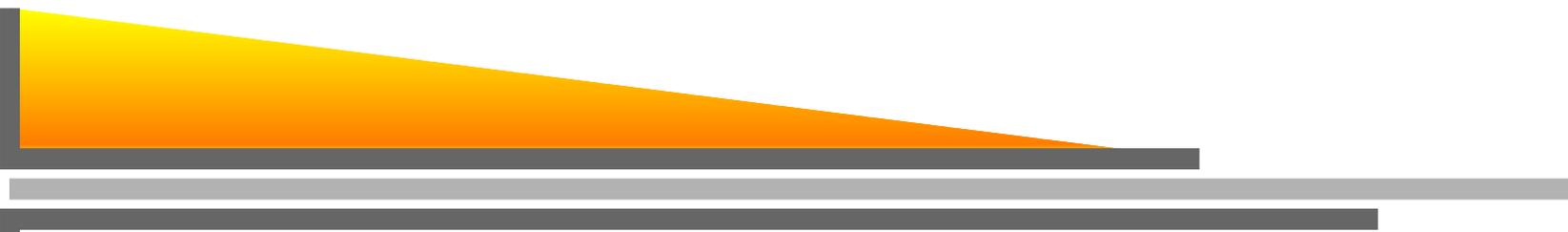


Calibration plots of FiveThirtyEight.com  
(as of June 2019)

# Calibration in Practice



Calibration plot of ElectionBettingOdds.com  
(2016 – 2018)



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## CONTINUOUS CALIBRATION:

- Each  $w_i(c)$  is a continuous function of  $c$  (“continuous fractional binning”)

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⇒ **Deterministic continuous** calibration

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# Forecast-Hedging $\mapsto$ Calibration

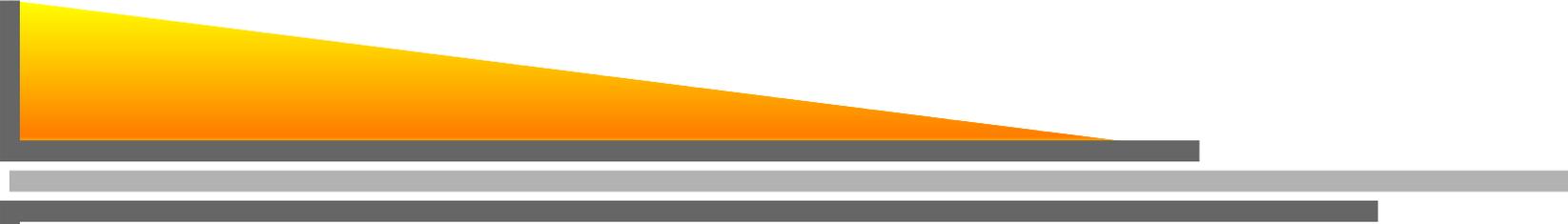
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- if  $f$  is continuous it holds also for  $\varepsilon = 0$

# Outgoing Theorems

## Outgoing **FIXED POINT (FP)**:

$f : C \rightarrow \mathbb{R}^m$  continuous function  
 $\Rightarrow \exists$  **POINT**  $y \in C$   
s.t.  $f(y) \cdot (c - y) \leq 0$  for all  $c \in C$

## Outgoing **MINIMAX (MM)**:

$f \rightarrow \mathbb{R}^m$  bounded function,  $\varepsilon > 0$   
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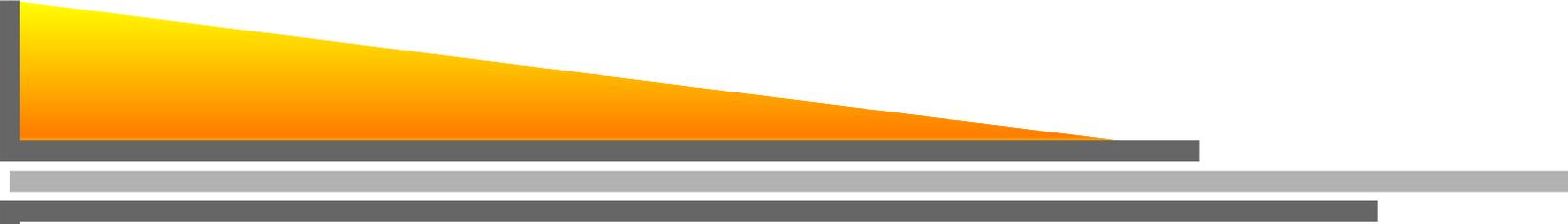
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$\forall \varepsilon > 0, \rho > 0 : \exists$   **$\rho$ -LOCAL STOCHASTIC**  
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Foster 1999, Kakade and Foster 2004



# Game Dynamics

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**General  $n$ -person game**

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⇒ Long-run play ?

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- ⇒  **$1 - \epsilon$  OF THE TIME** the play is a **NASH  $\epsilon$ -EQUILIBRIUM** in the long run (a.s.)

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In each period  $t$ , each player  $i$ :

1. runs the procedure (F) to get  $c_t$
2. plays  $g^i(c_t)$  given by (P)

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**CONTINUOUSLY CALIBRATED LEARNING:**

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$$\bullet g(\text{play}_t) = g(g(c_t)) \approx g(c_t) = \text{play}_t$$

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- **CONTINUOUS CALIBRATION**

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  - ⇒ *same* forecast for *all* players

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- ⇒ **FIXED POINT**

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  - *calibrated*
    - ⇒ forecast *equals* actions
  - ⇒ **FIXED POINT**
- **CONTINUOUS BEST REPLY**
  - ⇒ fixed point = **NASH EQUILIBRIUM**

# Dynamics and Equilibrium



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"LAW OF CONSERVATION OF COORDINATION":

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*There must be some* **COORDINATION** —

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# Dynamics and Equilibrium

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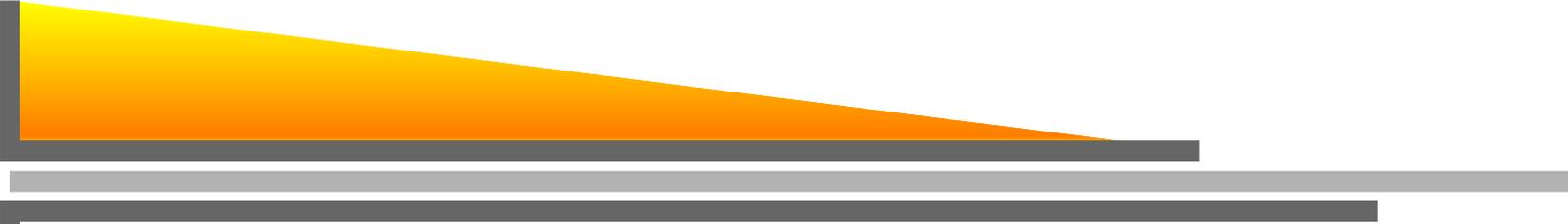
*There must be some* **COORDINATION** —

*either in the* **EQUILIBRIUM** *notion,*  
(**CORRELATED EQUILIBRIUM**)

*or in the* **DYNAMIC**  
(**NASH EQUILIBRIUM**)

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(Hart and Mas-Colell 2003)



# Summary

# Calibration, Dynamics, Equilibria

# Calibration, Dynamics, Equilibria

**MINIMAX** universe

# Calibration, Dynamics, Equilibria

**MINIMAX** universe

**FIXEDPOINT** universe

# Calibration, Dynamics, Equilibria

**MINIMAX** universe

- *stochastic*  
forecast-hedging

**FIXEDPOINT** universe

# Calibration, Dynamics, Equilibria

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# Calibration, Dynamics, Equilibria

## MINIMAX universe

- *stochastic*  
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- *MM*-procedures

## FIXEDPOINT universe

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forecast-hedging

# Calibration, Dynamics, Equilibria

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- *stochastic*  
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## FIXEDPOINT universe

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# Calibration, Dynamics, Equilibria

## MINIMAX universe

- *stochastic*  
forecast-hedging
- *MM*-procedures
- *classic*  
calibration

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## FIXEDPOINT universe

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- *FP*-procedures
- *continuous*  
calibration

# Calibration, Dynamics, Equilibria

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- *classic*  
calibration
- *correlated* equilibria

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- *continuous*  
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- *FP*-procedures
- *continuous*  
calibration
- *Nash* equilibria

# Calibration, Dynamics, Equilibria

## MINIMAX universe

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forecast-hedging
- *MM*-procedures
- *classic*  
calibration
- *correlated* equilibria
- *time-average*

## FIXEDPOINT universe

- *deterministic*  
forecast-hedging
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calibration
- *Nash* equilibria

# Calibration, Dynamics, Equilibria

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## FIXEDPOINT universe

- *deterministic*  
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- *FP*-procedures
- *continuous*  
calibration
- *Nash* equilibria
- *period-by-period*

# Perfect Hedging

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# Perfect Hedging



Château de Villandry, 2005