Definable sets over valued fields

Ehud Hrushovski

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Plan

- Review of basics on definable sets.
- Imaginaries. Joint work with Deirdre Haskell, Dugald Macpherson (monograph), Ben Martin (ArXiv)
- Topology. Joint work with François Loeser. (ArXiv, F.L. web page.)

- Definable types and generically stable types.
- Geometric imaginaries: sketch of proof.
- Topological finiteness: rough structure of proof.

K denotes a valued field.

- Algebraic varieties V. V(K) = points of V in a field K. For most of this talk, can think of V as affine, V(K) = {x ∈ Kⁿ : f₁(x) = ··· = f_k(x) = 0}.
- A semi-algebraic or constructible Z ⊂ V is defined by valuation inequalities such as valf ≥ valg; again Z(K) = {x ∈ V(K) : valf ≥ valg}, etc.
- \mathcal{O} is defined by: $valx \geq 0$.
- $(\Gamma, +, <)$ denotes the value group, val the valuation map. $\Gamma_{\infty} = \Gamma \cup \{\infty\}.$
- k is the residue field; res : $\mathcal{O} \rightarrow k$ the residue map.
- For a ∈ K and γ ∈ Γ denote B≥γ(a) (resp. B>γ(a)) the closed (resp. open) ball of valuative radius γ around a.

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Geometric imaginaries

•
$$S_n := GL_n/GL_n(\mathcal{O}) \cong B_n/B_n(\mathcal{O}).$$

►
$$T_n := GL_n/GL_n(\mathcal{O})^\circ$$
, where:
 $1 \to GL_n(\mathcal{O})^\circ \to GL_n(\mathcal{O}) \to GL_n(k) \to 1$ exact.

A definable subset of S_n or T_n is the image of a definable subset of GL_n. A definable map U → V is a definable subset f of U × V, that always defines a function.

$\succ \Gamma := S_1 = GL_1/GL_1(\mathcal{O}).$

- A linearly ordered group: +, < are definable (their pullbacks are ⋅, x ∈ Oy.)
- ▶ pure / QE: Any definable subset of Γⁿ is a Boolean combination of Q-linear inequalities.
- A natural topology, determined by the ordering. Γ_∞ := Γ ∪ {∞}.
- $\mathbf{k} = \mathcal{O}/\mathcal{M}$; $\mathbf{k}^* = GL_1(\mathcal{O})/GL_1(\mathcal{O})^\circ$; a pure field.
- ► RV := T₁ = GL₁/GL₁(O)^o also has a definable set structure that can be explicitly described;

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We will occasionally consider $Th(\mathbb{Q}_p)$, where quantifers range over \mathbb{Q}_p and not over the algebraic closure. The principal difference is that Γ is now discrete; QE still holds if *arithmetic sequences* are added to the basic structure.

Theorem (H., Haskell, Macpherson)

$$X_u = X_v \iff f(u) = f(v)$$

- ▶ Equivalent statement: Let $E \subset U^2$ be a semi-algebraic equivalence relation. Then there exists *n*, a definable subgroup $H \leq GL_n(\mathcal{O})$ as above, and a definable embedding $U/E \rightarrow GL_n/H$.
- ► The same result holds for definabity in Q_p. In this case, only the S_n are needed. (H.-Martin)
- Probably also for ultraproducts of the Q_p. (Certain cases, conjectured by Cluckers-Denef, proved.)
- All proofs use same strategy: study germs for definable types; geometry of definable types in terms of generically stable types. To be explained.

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Corollary (Rationality)

Let $X \subset \Gamma \times U$, $E \subset \Gamma \times U \times U$ be $Th(\mathbb{Q}_p)$ -definable, such that E_n is an equivalence relation on X_n , with a finite number of classes $\alpha(n)$.

Then piecewise, $\alpha(n)$ is an exponential polynomial $\sum b_{kl}n^kp^{ln}$.

Piecewise: divide \mathbb{N} according to residue mod some M, with a finite exceptional set. Combinatorial formulation: $\sum \alpha(n)t^n$ is rational.

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- ▶ Denef (1984) showed the same statement for *p*-adic integrals $\beta(n) = \int_{\mathbb{Q}_n^m} f(x, n) dx$ varying definably with $n \in \Gamma$.
- Denef's theorem is now understood as part of motivic integration; cf. Scanlon's talk. It can be shown via iterated integration, reduction to dimension one.
- Let μ be the right invariant volume form on GL_n . If X is a finite set of right $GL_n(\mathcal{O})$ -cosets, then $|X/GL_n(\mathcal{O})| = (\int 1_X d\mu)/(\int 1_{GL_n(\mathcal{O})} d\mu)$.
- ▶ By elimination of imaginaries, every equivalence relation reduces to the one above (*GL_n*(*O*)-cosets).
- Hence counting reduces to volumes.
- In fancy language: the Grothendieck ring of definable sets, even of imaginary sorts, maps into the Grothendieck ring of normalized volumes.

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- ► H. Martin. Irreducible representations of finitely generated nilpotent groups, up to 1-dimensional twists.
 - G.S. U_n(Z_n), U_n—upper triangular matrices. G has infinitely may 1-dimensional representations, but up to tensoring with them, only finitely many (a_n) irreducible continuous representations of dimension p². Then again (2) a_nC² is rational. Here X=1-dimensional representations of subgroups; E= same induced representation to G, up to a twist.

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From now on we will restrict attention to the theory $ACVF_F$ of algebraically closed valued fields, containing a given valued field F. Thus for subsets of algebraic varieties, semi-algebraic = constructible = definable (Robinson.) For subsets of the imaginary sorts, we prefer the term "definable".

- ► V an algebraic variety over F. A Berkovich point is a Grothendieck point, i.e. a K-irreducible subvariety U of V, along with an extension to F(U) of the valuation on F into the same group A.
- ▶ B_F(V) denotes the set of Berkovich points. If X is cut out of V by some valuation inequalities, let B_F(X) be the subset where these inequalities hold.
- ▶ Let f be a regular function on V. For any $p = (U_p, v_p) \in B_F(V)$, have $\operatorname{val} f(p) := v_p(f|U) \in \mathbb{R}$. Thus while f does not extend to $B_F(V)$, $\operatorname{val} \circ f$.
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We consider the Berkovich topology of *algebraic varieties*. We are given a valued field F, an ordered group A and a valuation $v : F \to A \cup \{\infty\}$. Mostly (with Berkovich) we will consider only the $A = \mathbb{R}$.

- ► V an algebraic variety over F. A Berkovich point is a Grothendieck point, i.e. a K-irreducible subvariety U of V, along with an extension to F(U) of the valuation on F into the same group A.
- ▶ B_F(V) denotes the set of Berkovich points. If X is cut out of V by some valuation inequalities, let B_F(X) be the subset where these inequalities hold.
- ▶ Let *f* be a regular function on *V*. For any $p = (U_p, v_p) \in B_F(V)$, have $\operatorname{val} f(p) := v_p(f|U) \in \mathbb{R}$. Thus while *f* does not extend to $B_F(V)$, $\operatorname{val} \circ f$.

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Let X be a definable subset of a quasi-projective variety V. Theorem (H.-Loeser)

- 1. There exists a deformation retraction from $B_F(X)$ to a subspace S homeomorphic to a finite simplicial complex.
- 2. Let $f : X \to Y$ be a morphism, $X_b = f^{-1}(b)$. Then there are finitely many possibilities for the homotopy type of $B_F(X_b)$, as b runs through Y(F).

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In the model-theoretic treatment, Berkovich points are replaced by generically stable types. The set of generically stable types on X is denoted \hat{X} .

They are defined for any valued field, not necessarily with value group $\subset \mathbb{R}$. This is related to the finiteness theorem (2). We will define the points from several viewpoints; show that they form a pro-definable set; define a topology on this set; and discuss the relation of $\widehat{X}(F)$ to $B_F(X)$, when the latter is defined. But first we must consider a more general notion, of a definable type. Asides from serving as a natural setting for picking out the generically stable types, we will use them to define and prove most of the significant properties of \widehat{X} ,

• $T = ACVF_F$, $L = +, \cdot, val$

Definition

Let $\mathcal{M} \models T$ and $A \subseteq M$. A type $p(x) \in S_n(M)$ p is A-definable if for every L formula $\phi(x, y)$ there is an L_A -formula $d_p\phi(y)$ s.t.

 $\phi(x,b) \in p \iff \mathcal{M} \models d_p \phi(b)$ (for every $b \in M$)

We say p is definable if it is definable over some $A \subseteq M$. The collection $(d_p \phi)_{\phi}$ is called a defining scheme for p.

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Remark

If $\rho \in S_{\delta}(M)$ is definable via $(d_{\rho}\phi)_{\delta}$, then the same scheme gives rise to a (unique) type over any $N \succ M$, denoted by $\rho \mid N$.

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I prefer to take the defining scheme itself to be the definable type.

Definition A definable type p(x) is a Boolean retraction $L_{x,y_1,y_2,...}$ to $L_{y_1,y_2,...}$,

 $\phi \mapsto (d_p x) \phi$

Analogy: a *finite measure* on a compact space X can be defined as a retraction from continuous functions on $X \times Y$, to continuous functions on Y.

Example, $Th(\mathbb{C})$: let V be an irreducible variety. $(d_p x)\phi = "$ for generic $x \in V$, $\phi" =$ for some proper Zariski closed $Z \subset V$, $(\forall x \in V \smallsetminus Z)\phi$.

Example, $Th(\mathbb{R})$ Let V be a variety and let $g : (a, b] \to V$ be a parameterized curve. $(d_p x)\phi =$ "for all t sufficiently close to b, $\phi(g(t))$. Definition of definable compactness in o-minimality. In ACVF, both kinds of example occur; in fact we will see that every definable type decomposes into a composition of the two.

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Operations on definable types (from M.H. tutorial)

- (Realised types are definable) Let $a \in M^n$. Then tp(a/M) is definable. (Take $d_p\phi(y) = \phi(a, y)$.) constant definable types
- (Preservation under definable functions)
 Let b ∈ dcl(M ∪ {a}), i.e. f(a) = b for some M-definable function f. Then, if tp(a/M) is definable, so is tp(b/M).
 Pushforward, f_{*}p:

 $(d_{f_*p}y)\theta(y,u) := (d_px)\theta(f(x),u)$

- ▶ (**Transitivity**) Let $a \in N$ for some $\mathcal{N} \succ \mathcal{M}$, $A \subseteq M$. Assume
 - r = tp(a/M) is A-definable;
 - tp(b/N) is $A \cup \{a\}$ -definable. so tp(b/N) = h(a)

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Definable types: germs and limits

- Let f, g be definable functions. f, g have the same p-germ if (d_px)(f(x) = g(x)) (iff whenever c ⊨ p|M, where f, g are defined oer M, we have f(c) = g(c).)
- Assume f : D → X, p a definable type on X, and X carries a (definable) topology. Write lim_p f = a if for any definable open U of a, a ∈ U ⇒ (d_px)(f(x) ∈ U)

- 1. Definable types, orthogonal to the value group: f_*p for any $f: V \to \Gamma$.
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- 4. (When $V \leq \mathbb{A}^n$ is an affine variety). Γ -seminorms $\nu : K[X_1, \dots, X_n] \rightarrow \Gamma_{\infty}$ $\nu(fg) = \nu(g) + \nu(g), \nu(f+g) \geq \min(\nu(f), \nu(g)), \nu(c) = \operatorname{val}(c)$ such that $\nu(f) = \infty$ if f|V = 0, and $\nu|K[X_1, \dots, X_n]_d$ is definable, for each d
- 5. (When Γ(F) ≤ ℝ). An element of B_F(V), functorially extendible to B_{F'}(V) for F' ≥ F As Antoine Ducros pointed out, for this statement we must consider arbitrary F'; for those with value group ℝ, a theorem of Poineau extends any Berkovich point functorially.

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- An *F*-definable, generically stable type need not be dominated by an *F*- definable map into kⁿ. The vector space *E* may have the form Λ/*M*Λ, Λ an *F*-definable lattice.
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Proof of equivalence

- ▶ 2 ⇒ 3 Since p is determined by g_*p , and $g_*p \otimes q = q \otimes g_*p$.
- 3 ⇒ 1: Symmetry implies symmetry of pushfoward. A type on Γ commuting with itself is constant.

► 1 ⇒ 4
$$\nu(f) = (\operatorname{val} f)_* p$$
.

 1 ⇒ 2 follows from the decomposition theorem over maximally complete fields below, and a (still quite technical) descent theorem for stably dominated types.

► 4 ⇒ 1:
$$(d_p x)(\operatorname{val} f \ge \operatorname{val} g) \iff \nu(f) \ge \nu(g).$$

▶ $1 \Rightarrow 5$ as definable types give types over any larger base.

• $5 \Rightarrow 1$: example of type 4 point.

• *F* be a valued field, with value group $\leq \mathbb{R}$.

- F^{max} a spherically complete algebraically closed field, containing F, with value group ℝ, and residue field equal to the algebraic closure of the residue field of F. (unique up to isomorphism, by Kaplansky's theorem.)
- $\pi = \pi_X : \widehat{X}(F^{max}) \to B_F(X)$ (realization and restriction.)
- π_X is surjective.
- π is functorial in X. $\pi(\Gamma) = \mathbb{R}$.
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Proposition

Let M be a spherically complete valued field, N = M(a) a valued field extension. Let $\gamma = (\gamma_1, ..., \gamma_n)$ be a basis for $\Gamma(N)/\Gamma(M)$. Then there exists a unique $M(\gamma)$ -definable type extending $tp(a/M(\gamma))$. This type is stably dominated.

Call a lattice Λ diagonal for a basis (b_1, \ldots, b_n) if there exist $c_1, \ldots, c_n \in K$ with $\Lambda = \sum Oc_i b_i$. In other words, $\Lambda = \bigoplus_i \Lambda \cap K b_i$ Proposition

let D be a Γ -internal set of lattices, i.e. there exists a surjective map $\Gamma^m \to D$. Then there exist a finite partition $D = \bigcup_{i=1}^r D_i$ and bases b^1, \ldots, b^r such that each $\Lambda \in D_i$ is diagonal in b^i .

Decomposition theorem

Theorem

Let p be an A-definable type on a variety V. Then there exist an A-definable type r on Γ^n and an A-definable r-germ of pro-definable maps into \hat{V} , with $p = \int_r f$.

Example

Definable types on a curve *C* correspond to germs of definable paths on $\alpha : [a, b] \subset \Gamma \rightarrow \widehat{C}$. Generically stable types correspond to constant paths.

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- $n \leq \dim(V)$.
- The theorem holds also for *invariant types*, meaning a functorial Huber-Knebush point; r is then an invariant type on Γⁿ.
- r and the r-germ of f are unique up to reparameterization; a canonical additional constraint on the parameterization of f exists.
- *f* itself may not exist over *A*, but only over a bigger base field.
 E.g., when *p*=*p*_B= generic type of an open ball.

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- Let A be a set of abstract imaginaries. Let D ⊂ Kⁿ be a nonempty A-definable set. Then there exists a definable type p on D (over U) such that p has a finite orbit under Aut(U/A). reduces to dimension 1.
- Any definable type has a canonical base B ⊂ S_n × T_n × Kⁿ, some n. (A unique minimal base of definition.) uses decomposition theorem.
- Let E be a definable equivalence relation on Aⁿ, let D be a class, a an (abstract) code for the class D. Let p be a definable type on D. Let b be the canonical base. Then D is b-definable, and b has finitely many a-conjugates b₁,..., b_m. Hence a is equivalent to a *finite set* of geometric imaginaries.
- Explicitly code finite sets of lattices by a higher-dimensional lattice.

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Let X be a definable subset of a quasi-projective variety V, over F. Theorem

- There exists a definable deformation retraction from X to a definable subspace Υ, and a definable homoeomorphism Υ → S ⊂ Γ^w_∞; w a finite set.
- 2. The image in S of any constructible $Y \subset X$ is definable using <, + alone. (A hint of tropicality.)
- Let f : X → Y be a morphism, X_b = f⁻¹(b). Then the retractions X_b → Y_b and definable homeomorphisms
 Y_b → S_b ⊂ Γ^w_∞ are uniformly definable; and as b runs through Y(F), there are finitely many possibilities for the homeomorphism type of S_b(ℝ_∞).

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Remarks

- w is the set of roots of a polynomial over F. Γ_∞^w is homeomorphic to Γ_∞^{|w|}; we use w in order to have an Fdefinable homeomorphism; in particular, Galois invariant.
- Semi-linearity of the image is automatic: any (ACVF) definable subset of Γⁿ_∞ is <, +-definable.</p>
- Finite number of definable homotopy types: likewise automatic from the same statement in o-minimal case, once one notes that the family of skeleta S_b of the sets X_b, is uniformly definable. Any ACFA_F-definable subset of Γⁿ_∞ is <,+-definable with parameters from Γ(F).</p>

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- A definable homotopy is a continuous, pro-definable
 H: X × I → X, I a Γ-interval; with h_{minl} = Id, h_{maxl} = h₁.
 We seek a definable homotopy H to h₁ with h₁(X) ≅ S ⊂ Γ^w_∞.
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ACV^2F and continuity criteria

- ACV²F is the theory ACV²F of triples (K₂, K₁, K₀) of fields with surjective, non-injective places K₂ →_{r₂₁} K₁ →_{r₁₀} K₀.
- $\blacktriangleright \ 0 \to \Gamma_{10} \to \Gamma_{20} \to \Gamma_{21} \to 0$
- $V_{210} = V_{20}$. Hence $V_{20} \to V_{21}$.
- An ACVF-definable map $f: W \to V$ extends to a continuous map $\widehat{W} \to \widehat{V}$ if and only if it is compatible with the natural maps among \widehat{V}_{ij} .

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We obtain the deformation by a composition of four kinds of homotopies:

1. Deformations of (relative) curves.

Arrange (after a blowup with finite center) that V is fibered by curves over a variety U. Apply (1) to each curve V_u .

- Away from a divisor D_{out} on U_c and after a fiber product with a finite Galois cover of U_c obtain a deformation H on V with final image definably homeomorphic to a subset Ω of $U \propto \Gamma_{Cc}^{n}$
- 2. Extend deformation H_U of \widehat{U} to Ω .
- Pre-compose with *inflation homotopy* in order to get away from D_{vert}. This homotopy does not move singular points, and slightly inflates smooth points to generics of small polydisks around them.
- 4. These steps already yield H as stated; but one also wants a strong deformation, i.e. that H fixes $h_1(\hat{X})$.. This can be arranged by post-composing with a homotopy of $h_1(\hat{X})$. This fourth homotopy lives entirely in the tropical world.

We obtain the deformation by a composition of four kinds of homotopies:

1. Deformations of (relative) curves.

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